

Berkeley MAPP and VAPP

(**M**odel and **A**lgorithm **P**rototyping **P**latform)
(**V**erilog-**A** **P**arser and **P**rocessor)

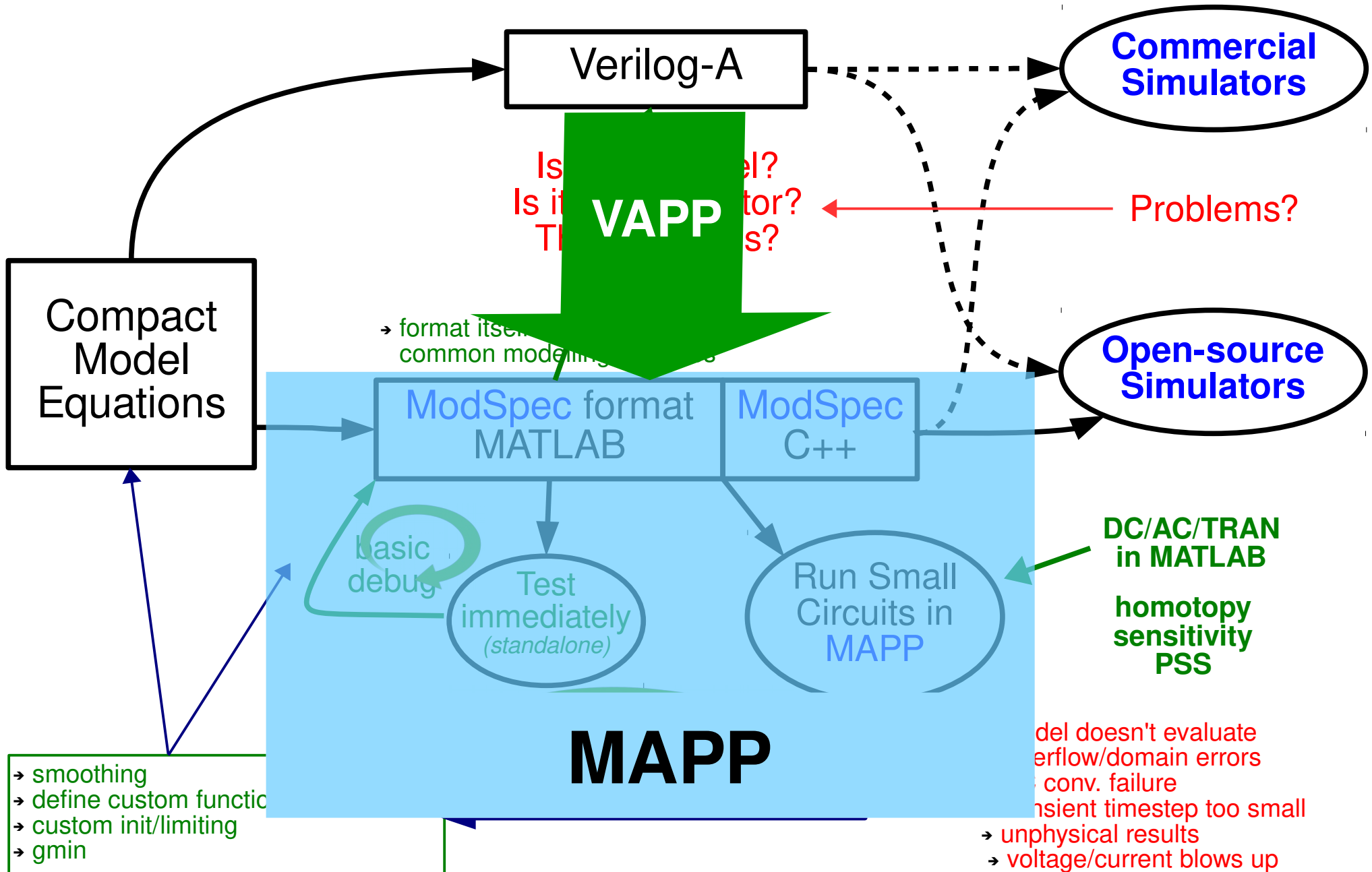
Tianshi Wang, A. Gokcen Mahmutoglu, Karthik Aadithya*,
Archit Gupta and Jaijeet Roychowdhury

EECS Department, University of California, Berkeley

*Sandia National Laboratories



Compact Model Development



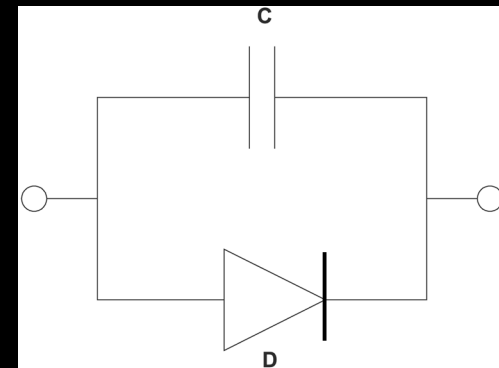
What's ModSpec: a glimpse

```

1 function MOD = diodeCapacitor_ModSpec_wrapper()
2 % ModSpec description of an ideal diode in parallel with a capacitor
3 MOD = ee_model();
4 MOD = add_to_ee_model(MOD, 'external_nodes', {'p', 'n'});
5 MOD = add_to_ee_model(MOD, 'explicit_outs', {'ipn'});
6 MOD = add_to_ee_model(MOD, 'parms', {'C', 2e-12, 'Is', 1e-12, 'VT', 0.025});
7 MOD = add_to_ee_model(MOD, 'f', @f);
8 MOD = add_to_ee_model(MOD, 'q', @q);
9 end
10
11 function out = f(S)
12     v2struct(S);
13     out = Is*(exp(vpn/VT)-1);
14 end
15
16 function out = q(S)
17     v2struct(S);
18     out = C*vpn;
19 end

```

"diodeCapacitor_ModSpec_wrapper.m" 19L, 548C written 1,1 All



MOD.terminals
 MOD.parms
 MOD.explicit_outs
 MOD.f: function handle
 MOD.q: function handle
 ...

$$\begin{aligned}
 \vec{z} &= \frac{d}{dt} \vec{q}_e(\vec{x}, \vec{y}) + \vec{f}_e(\vec{x}, \vec{y}, \vec{u}) \\
 \vec{0} &= \frac{d}{dt} \vec{q}_i(\vec{x}, \vec{y}) + \vec{f}_i(\vec{x}, \vec{y}, \vec{u})
 \end{aligned}$$

Diagram showing variables `ipn` and `vpn` in boxes with arrows pointing to the equations above. `ipn` points to the \vec{z} equation, and `vpn` points to the \vec{q}_e term in the same equation.

Differential Algebraic Equations

What's ModSpec: a glimpse

Executable &
debuggable
standalone

Easy to
examine/write
by hand

General:
any device in
any physical
domain

Easily &
directly
usable by
any simulator

Supports
every analysis
DC/AC/tr/PSS

Mathematically
well defined,
modular

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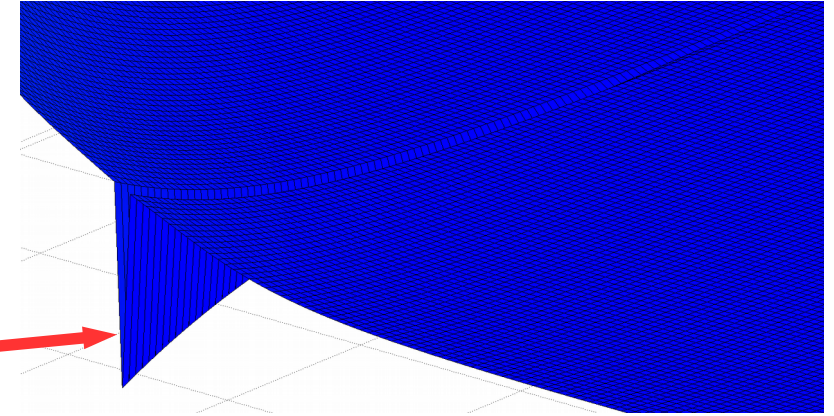
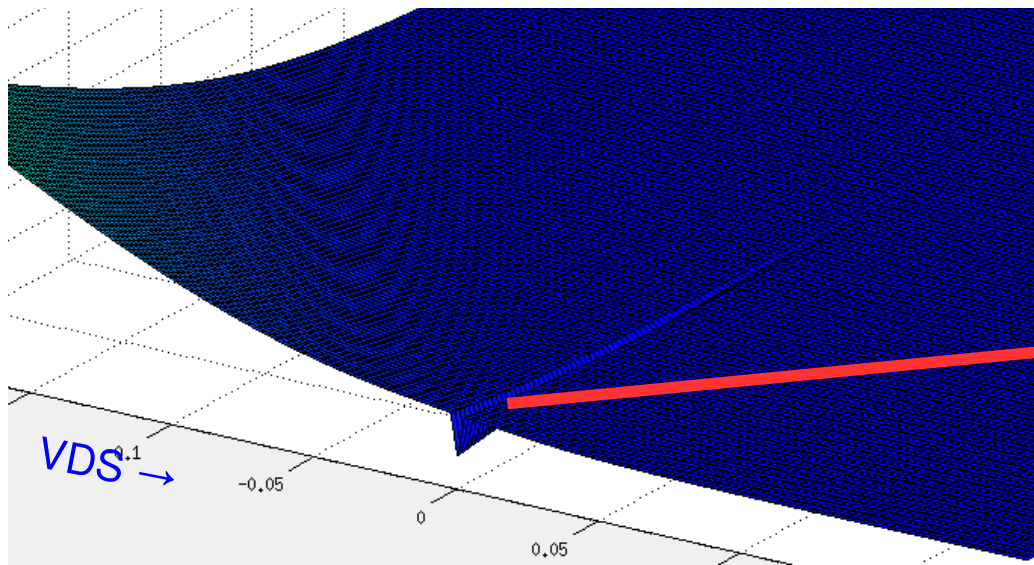
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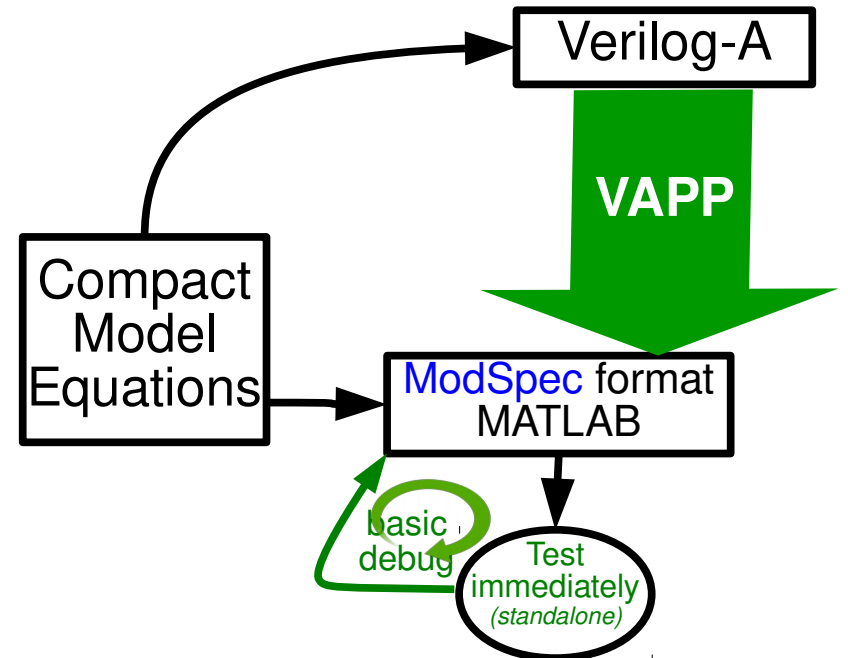
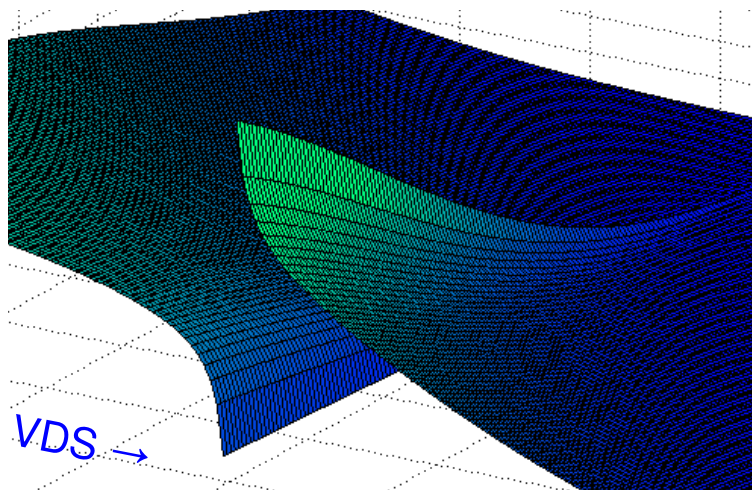
Differential Algebraic Equations

ModSpec: Model Debugging Example

MVS: "notch" in IDS at exactly $VDS = \text{zero}$



MVS: $dIDS/dVDS$



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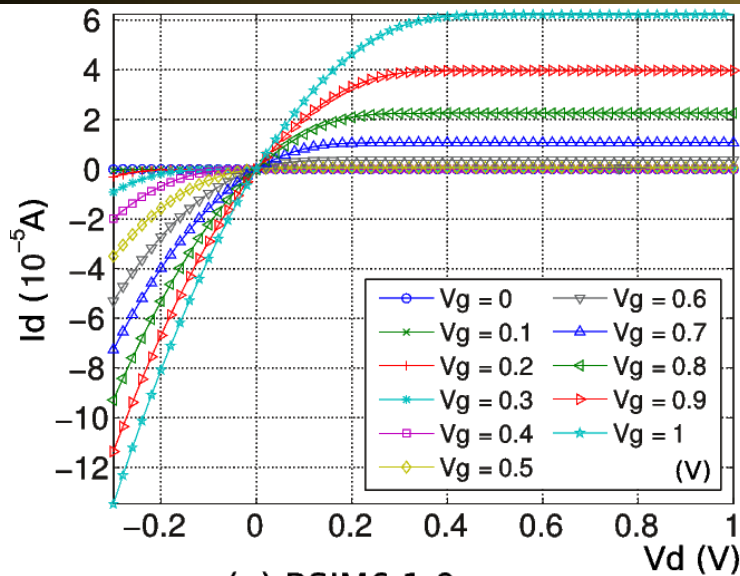
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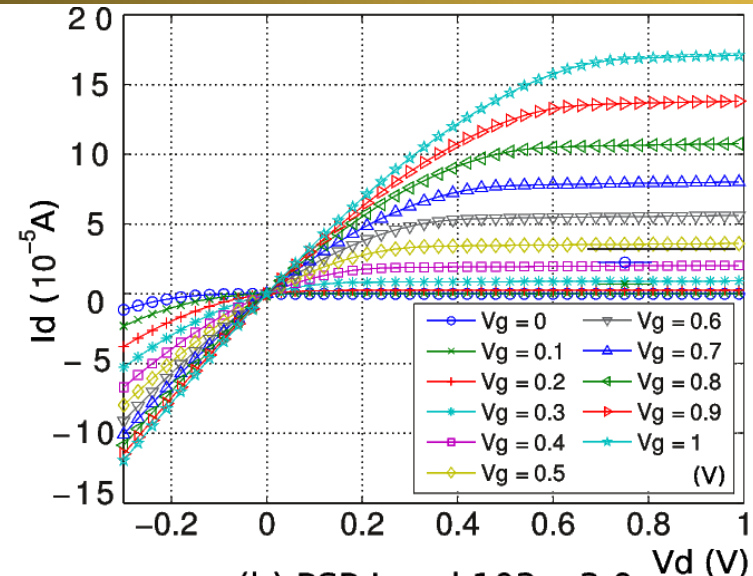
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Differential Algebraic Equations

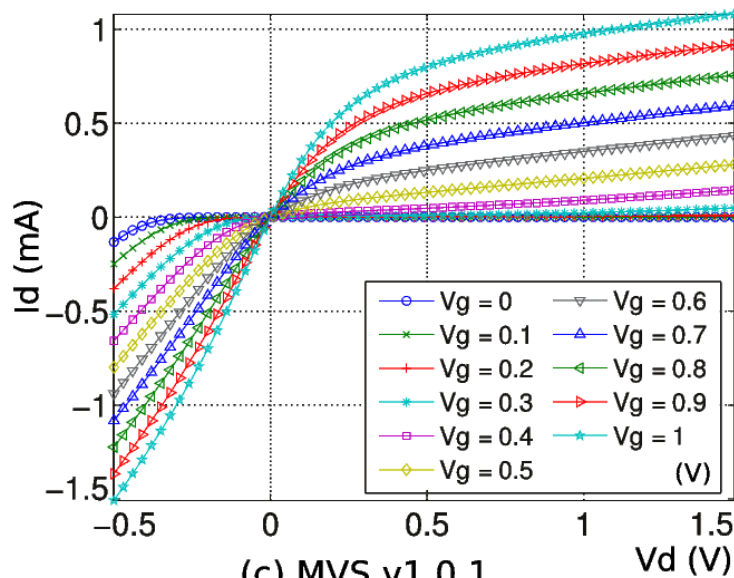
MAPP: Compact Model Prototyping



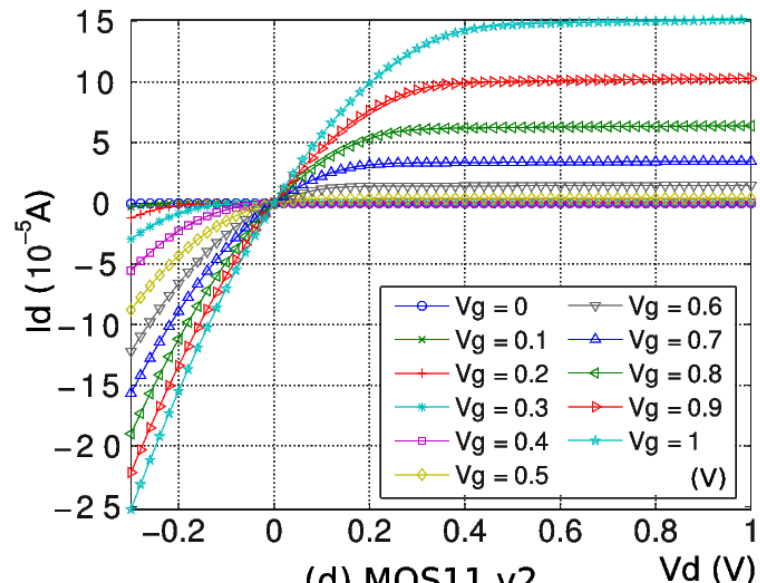
(a) BSIM6.1.0
default: $L=10\mu\text{m}$, $W=10\mu\text{m}$



(b) PSP Level 103 v3.0
default: $L=10\mu\text{m}$, $W=10\mu\text{m}$



(c) MVS v1.0.1
default: $L=80\text{nm}$, $W=1\mu\text{m}$



(d) MOS11 v2
default: $L=1\mu\text{m}$, $W=1\mu\text{m}$

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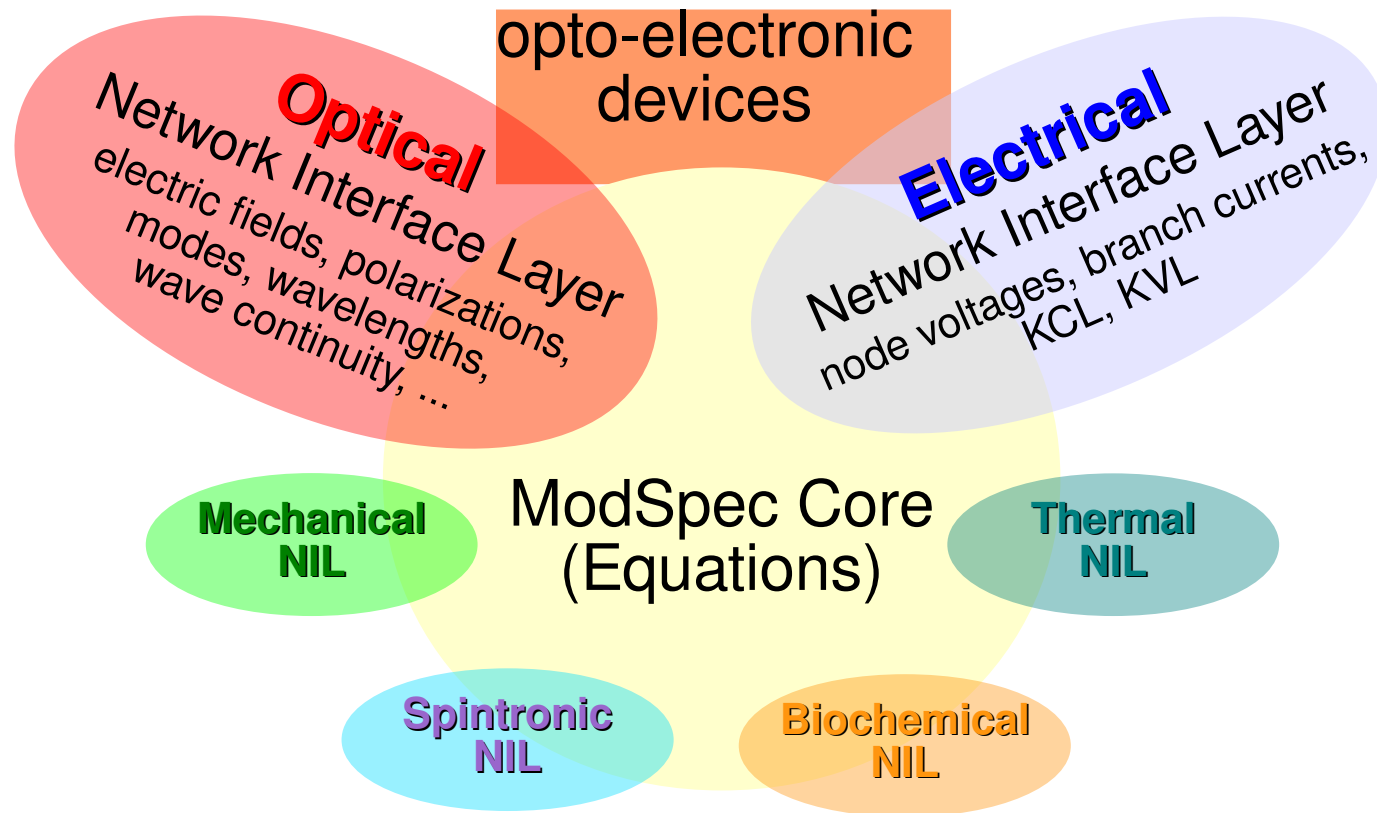
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Differential Algebraic Equations

ModSpec: Multiphysics Support



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Differential Algebraic Equations

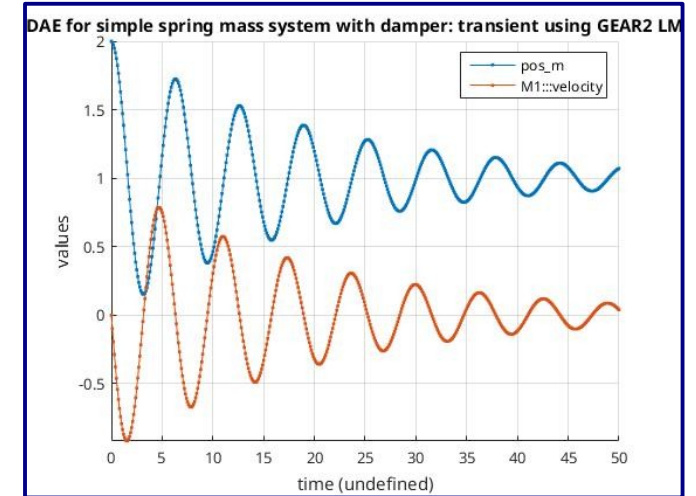
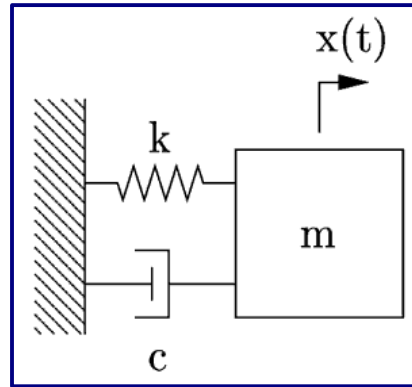
Multiphysics Systems

potential/flow systems:

kinematic NIL:

“flow”: force

“potential”: position



magnetic NIL:

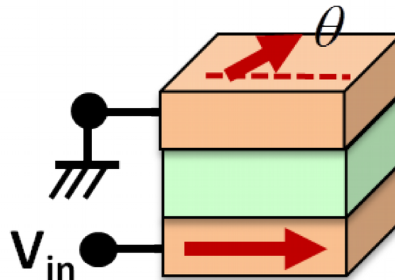
“flow”: magnetic flux

“potential”: magnetomotive force

thermal NIL:

“flow”: power flow

“potential”: temperature



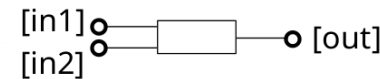
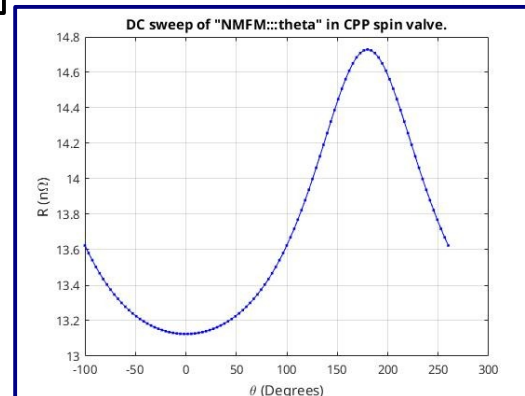
Chemical reaction networks

rates and concentrations

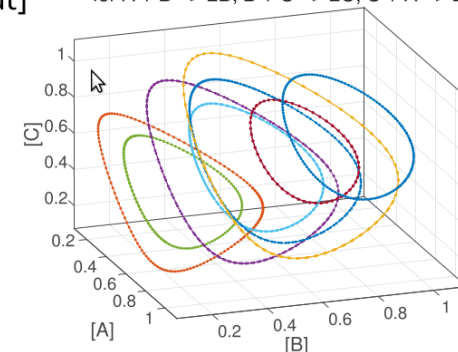
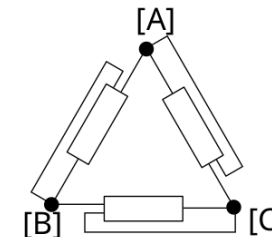
“KCLs” at nodes have d/dt terms

Spintronic systems:

vectorized spin currents
vectorized spin voltages



3D phase plane plot of RRE
for $A + B \rightarrow 2B$; $B + C \rightarrow 2C$; $C + A \rightarrow 2A$



Kerem Yunus Camsari; Samiran Ganguly;
Supriyo Datta (2013), "Modular Spintronics Library,"
<https://nanohub.org/resources/17831>.

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Differential Algebraic Equations

Glimpse: ModSpec Model in Xyce

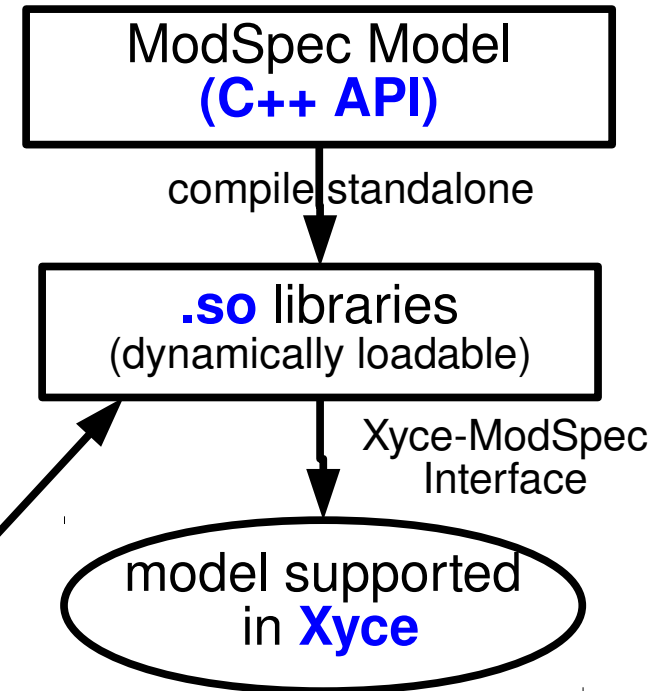
```
1 *** Test-bench for generating dc response of an inverter
2
3 *** Creat sub-circuit for the inverter
4 .subckt inverter Vin Vout Vvdd Vgnd
5
6 yModSpec_Device X1 Vvdd Vin Vout Vvdd:MVSmod:type=-1 W=1.0e-4
7   Lgdr=32e-7 dLg=8e-7 Cg=2.57e-6 beta=1.8 alpha=3.5 Tjun=300
8   Cif = 1.38e-12 Cof=1.47e-12 phib=1.2 gamma=0.1 mc=0.2
9   CTM_select=1 Rs0=100 Rd0 = 100 n0=1.68 nd=0.1 vx0=7542204
10  mu=165 Vt0=0.5535 delta=0.15
11
12 yModSpec_Device X0 Vout Vin Vgnd Vgnd:MVSmod:type=1 W=1e-4
13   Lgdr=32e-7 dLg=9e-7 Cg=2.57e-6 beta=1.8 alpha=3.5 Tjun=300
14   Cif=1.38e-12 Cof=1.47e-12 phib=1.2 gamma=0.1 mc=0.2
15   CTM_select=1 Rs0=100 Rd0=100 n0=1.68 nd=0.1 vx0=1.2e7
16   mu=200 Vt0=0.4 delta=0.15
17
18 .model MVSmod MODSPEC_DEVICE SONAME=MVS_ModSpec_Element.so
19
20 .ends
21
22 *** circuit layout
23 Vsup sup 0 1
24 Vin in 0 0
25 Vsource source 0 0
26 X2 in out sup 0 inverter
27
28 *** simulation
29 .dc Vin 0 1 0.01
30
31 .print dc V(in) V(out)
32 *** END
33 .end
```

.model line

model's name

model parameter:
name of .so library

**Xyce netlist for inverter
(using MVS ModSpec/C++ model)**



Updates in the last year

- limiting correction
- composite parameters
- works in Xyce 6.5

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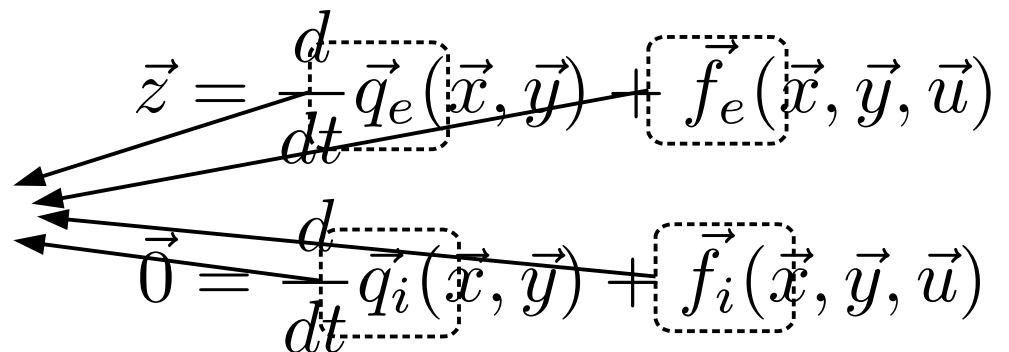
Differential Algebraic Equations

STEAM: Fast, Accurate Table-Based Models

- Compact model using only tabulated i-v, q-v data?
 - » previous table-based attempts: important details unclear, poor accuracy, low speedup
 - » our goal: can we speed up existing compact models?
- Our approach: STEAM
 - » tabulate ModSpec functions f_e, f_i, q_e, q_i (one time cost)
 - » device eval: multi-dimensional cubic spline interpolation
- Initial results
 - » 150x eval speedup for BSIM3 (6-15x tran/DC)
 - » relative error as low as you like: eg, 10^{-4}
 - but memory requirements grow with accuracy

replace with “lookup” tables

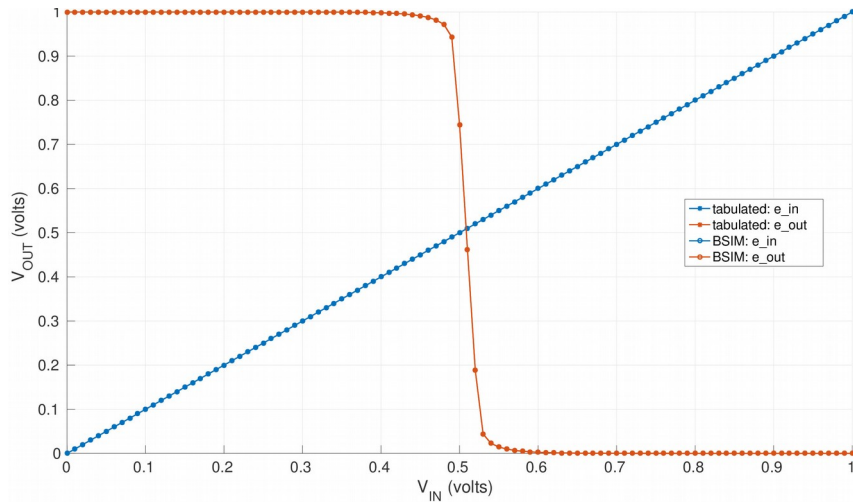
implementation details:
multi-dimensional splines,
passive extrapolation

$$\vec{z} = \frac{d}{dt} \vec{q}_e(\vec{x}, \vec{y}) + \vec{f}_e(\vec{x}, \vec{y}, \vec{u})$$
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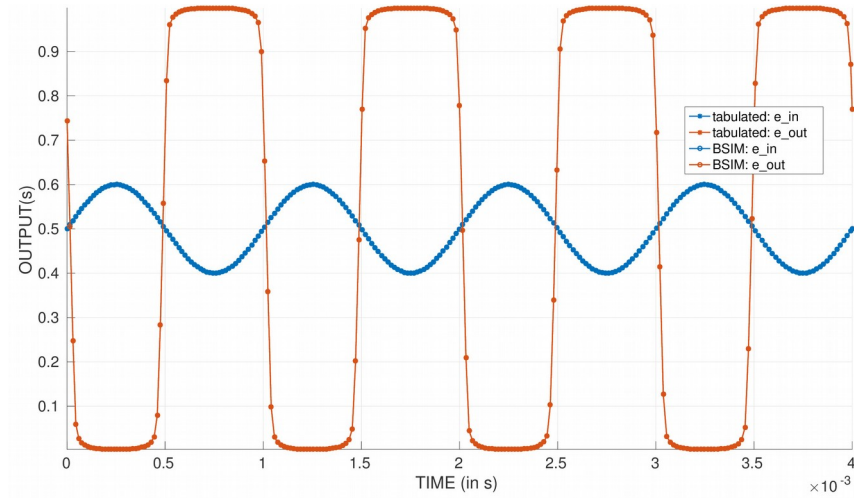
Differential Algebraic Equations

BSIM3 Inverter: STEAM vs Original

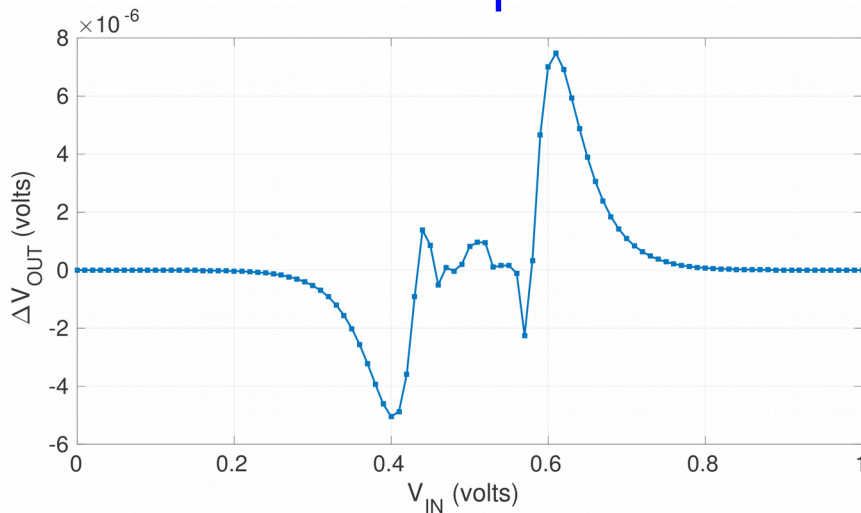
DC sweep



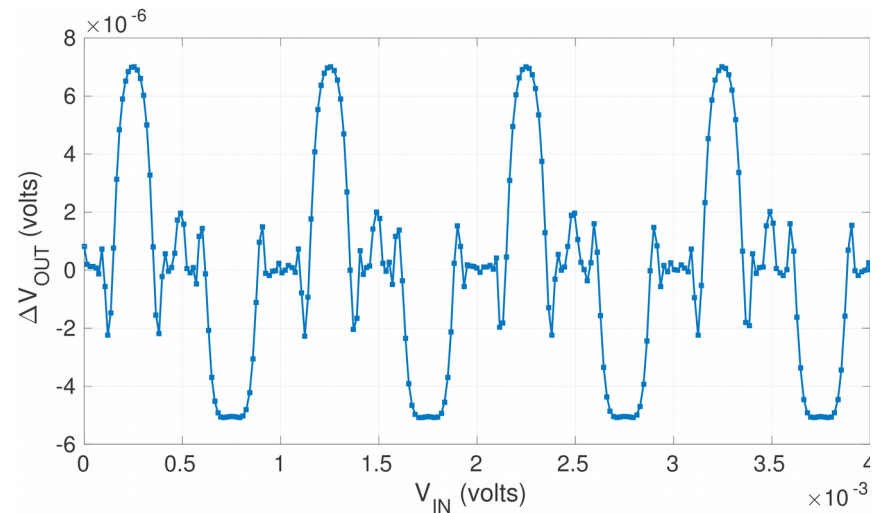
Transient



DC sweep: error



Transient: error



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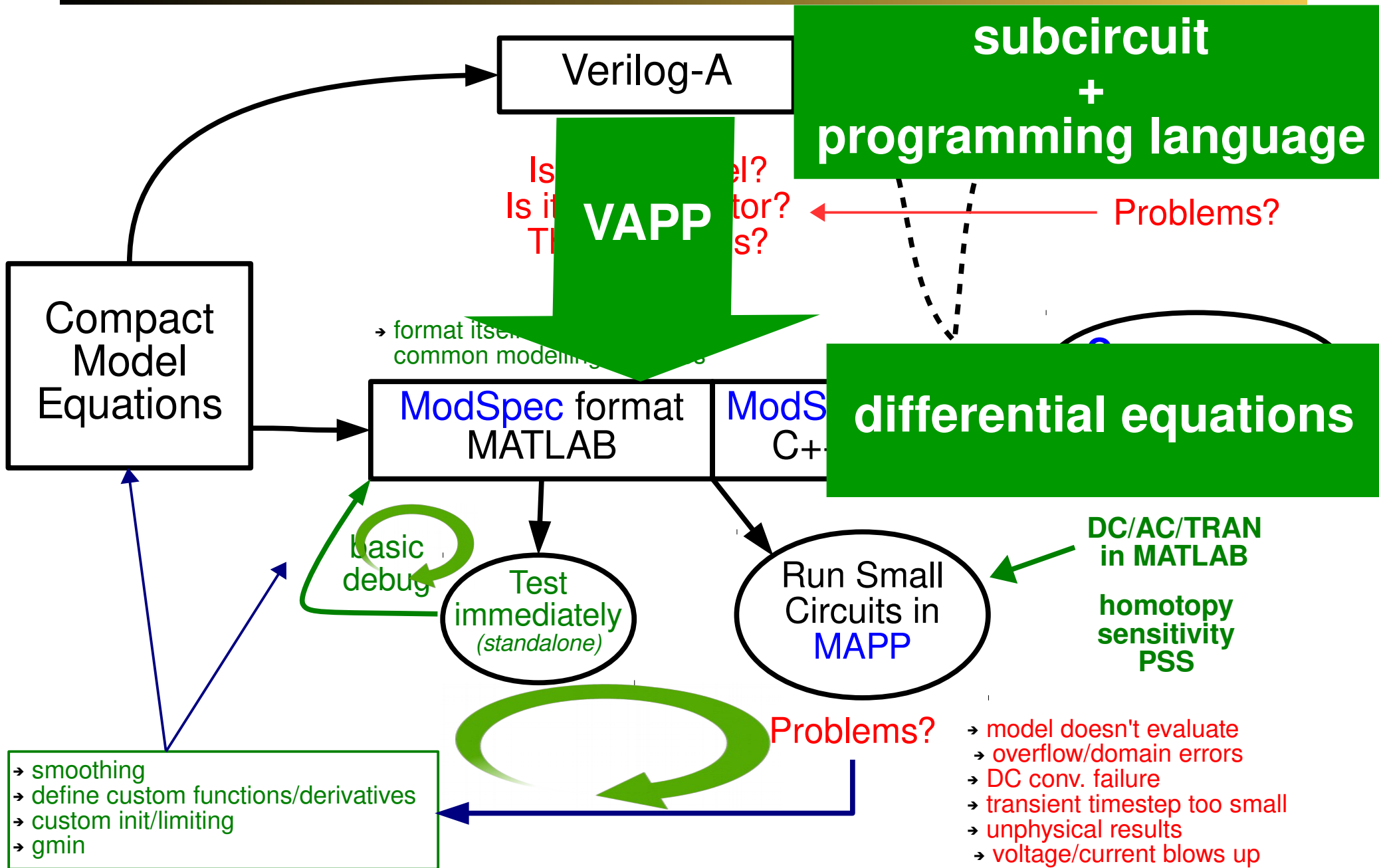
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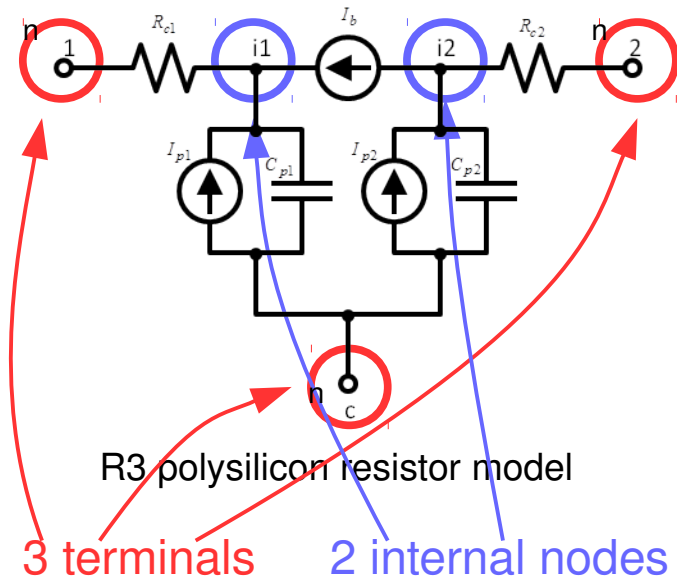
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Differential Algebraic Equations

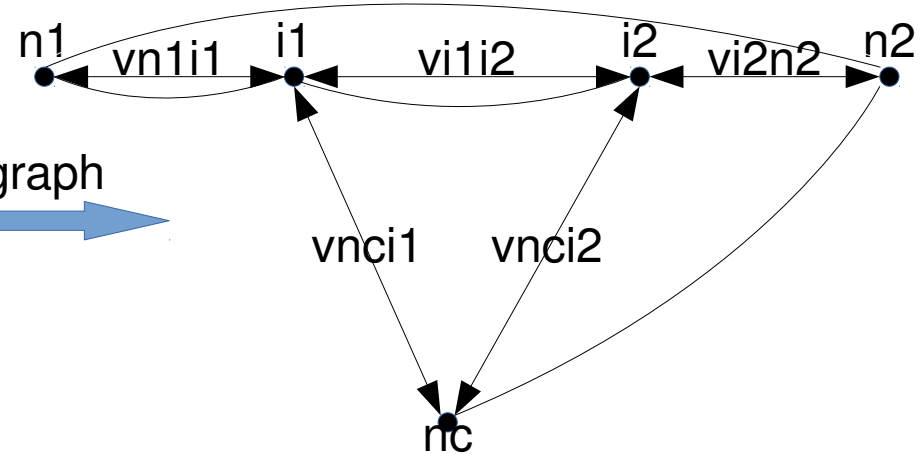
Compact Model Development



VAPP: New Graph Based Core



Convert to a graph



How do we know that $\{vn1i1, vi1i2\}$ are internal unknowns?

And $\{vnci1, vnci2\}$ dependent voltages?

Algorithm:

- Construct a **spanning tree** (ST)
- Designate branches in the ST as independent voltages
- Remaining branches are independent currents
- Construct **loop** and **cutset matrices**
- Express dependent quantities in terms of independent ones

VAPP: What Is Still Lacking?

- Node collapse:

```
if (rdsmod == 0)
  begin
    V(source, sourcep) <+ 0;
    V(drainp, drain) <+ 0;
  end
else
  begin
    I(drain, drainp) <+ type * gdtot * vded;
    I(source, sourcep) <+ type * gstot * vses;
  end
end
```

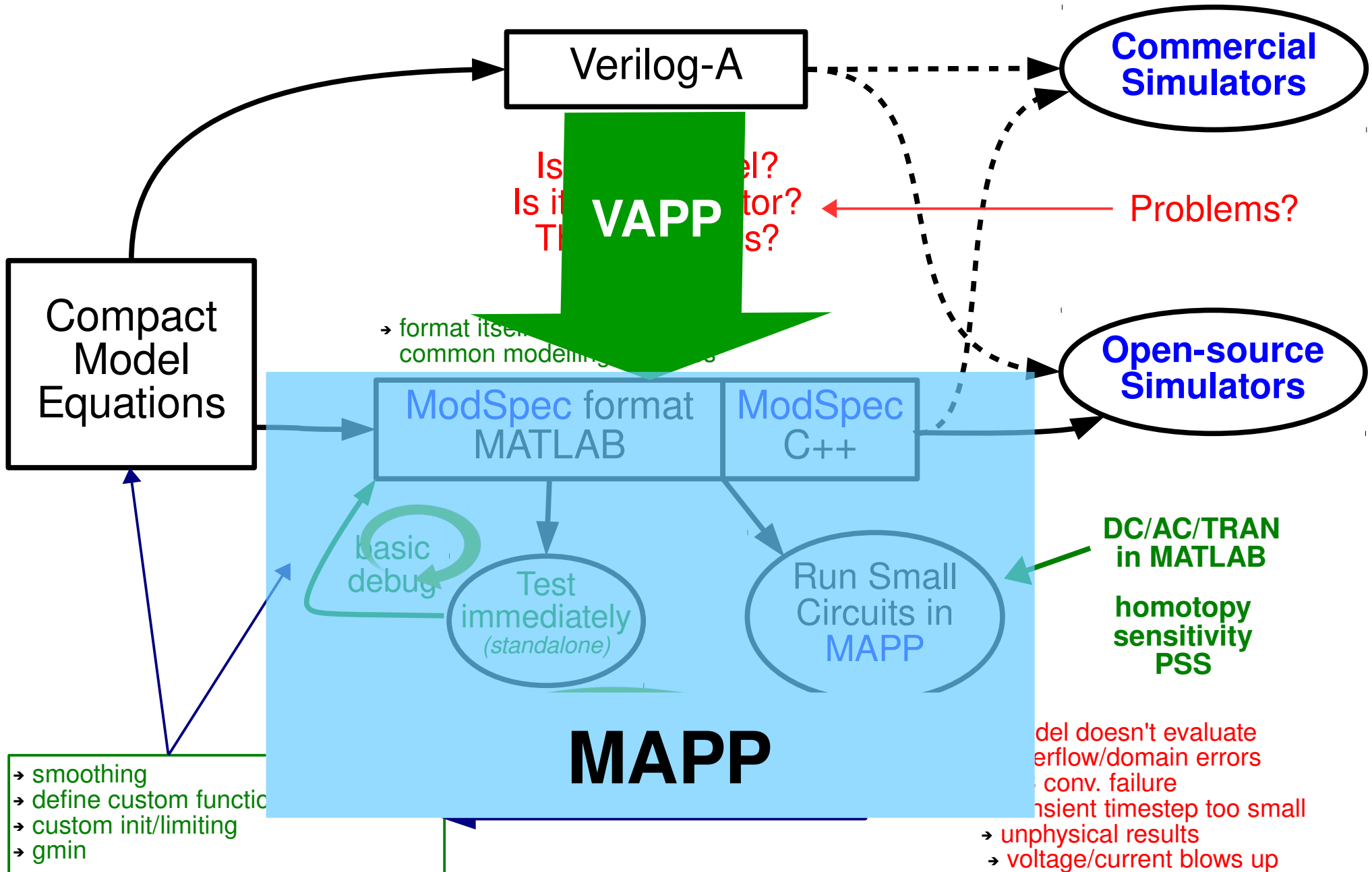


Changes the
number of
unknowns.

- Separate networks (graphs) for different disciplines. E.g., `thermal`, `magnetic`, ...
Important for self heating.

- Support for noise functions in MAPP. E.g., `white_noise`, `flicker_noise`

Compact Model Development

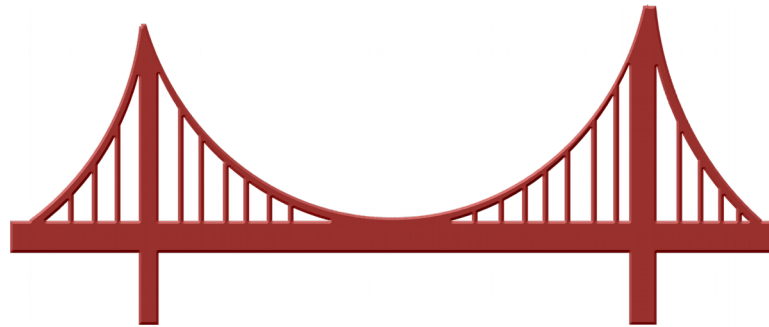


Memristive Devices & Applications

devices

UMich, Stanford,
HP, HRL Labs,
Micron, Crossbar,
Samsung, ...

Knowm



applications

- nonvolatile memories
- FPAAs
- neuromorphic circuits
- oscillators

Compact Models

- Linear/nonlinear ion drift models

Biolek (2009), Joglekar (2009),
Prodromakis (2010), et al.

- UMich RRAM model (2011)

- TEAM model (2012)

- Simmons tunneling barrier model
(2013)

- Yakopcic model (2013)

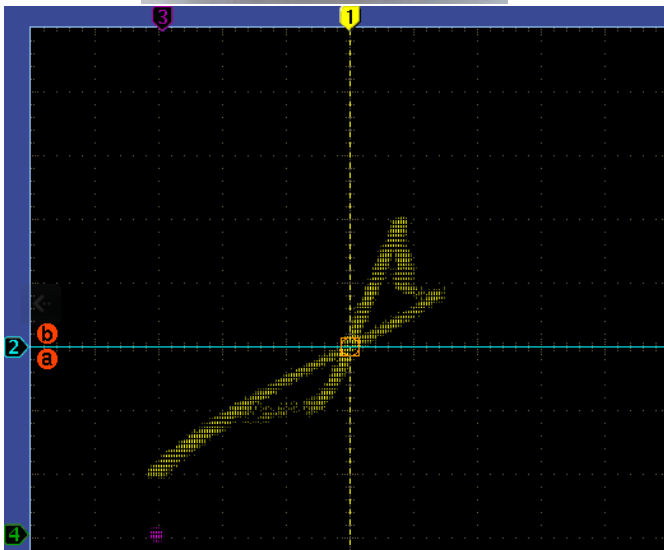
- Stanford/ASU RRAM model (2014)

- Knowm “probabilistic” model (2015)

not one works in DC

Verilog-A problems

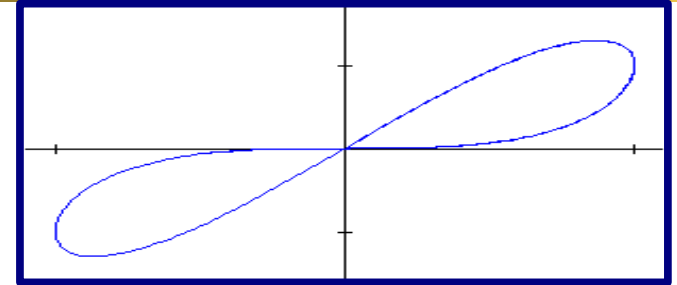
idt(), \$bound_step,
\$abstime, @initial_step,
\$rdist_normal, ...



Challenges in Memristor Modelling

- hysteresis

- internal state variable



- model internal unks in Verilog-A

- use potentials/flows

- upper/lower bounds of internal unks

- filament length, tunneling tap size

- clipping functions

- smoothness, continuity, finite precision issues, ...

- use smooth functions, safe functions

- GMIN

- scaling of unks/eqns

- SPICE-compatible limiting function (the only smooth one)

How to Model Hysteresis Properly

Template:

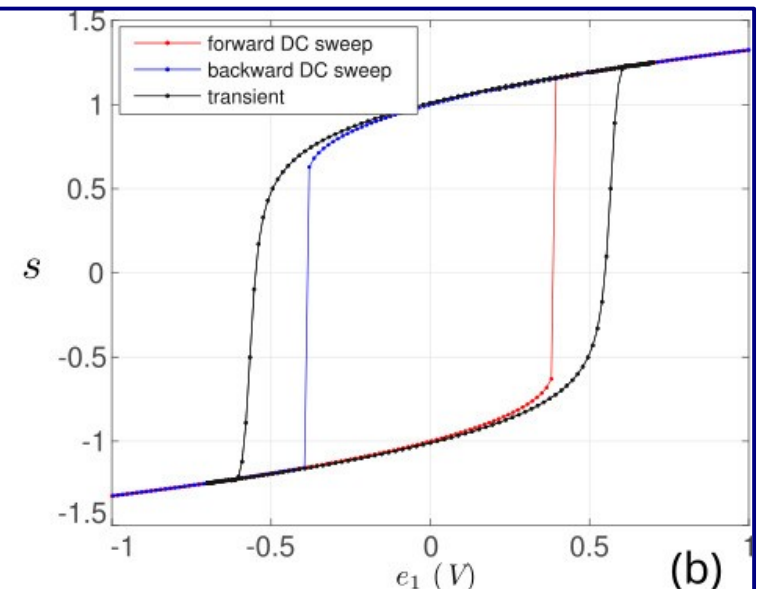
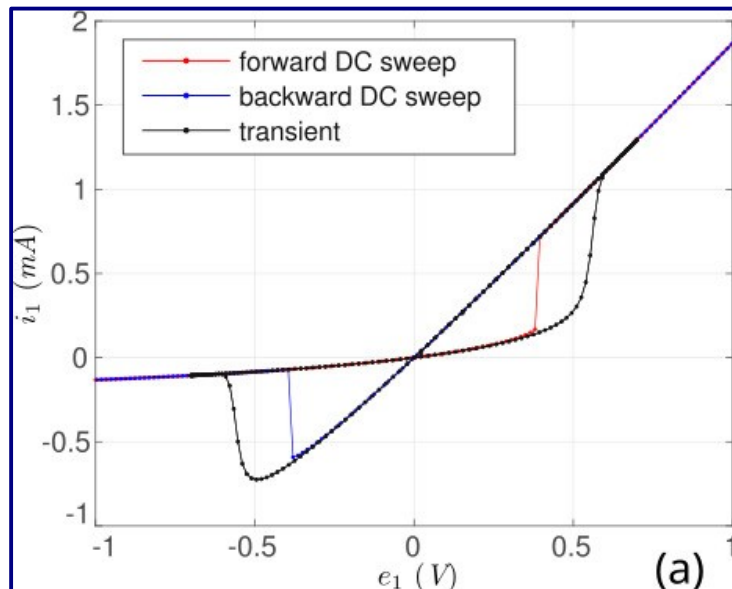
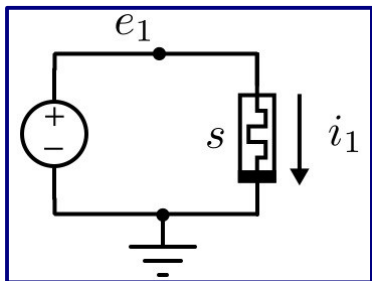
$$i_{pn} = f_1(v_{pn}, s)$$

$$\frac{d}{dt}s = f_2(v_{pn}, s)$$

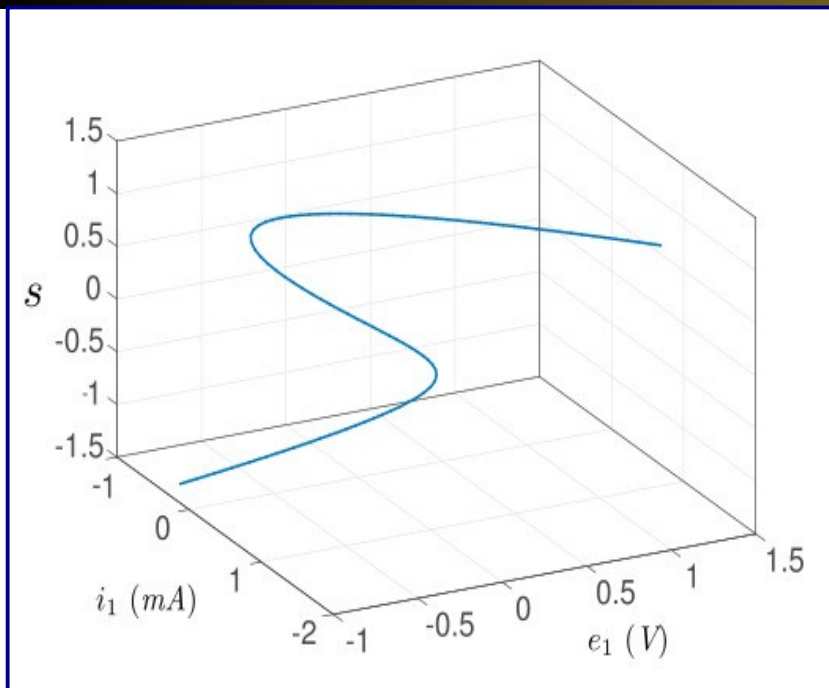
ModSpec:

$$i_{pn} = \frac{d}{dt} \underbrace{q_e(v_{pn}, s)}_{\mathbf{0}} + \underbrace{f_e(v_{pn}, s)}_{f_1}$$

$$0 = \frac{d}{dt} \underbrace{q_i(v_{pn}, s)}_{-s} + \underbrace{f_i(v_{pn}, s)}_{f_2}$$

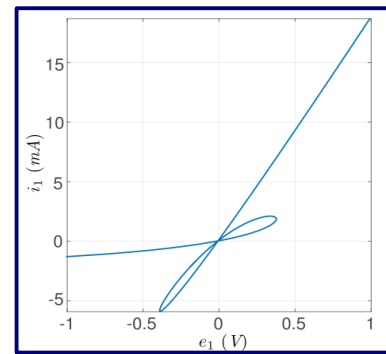


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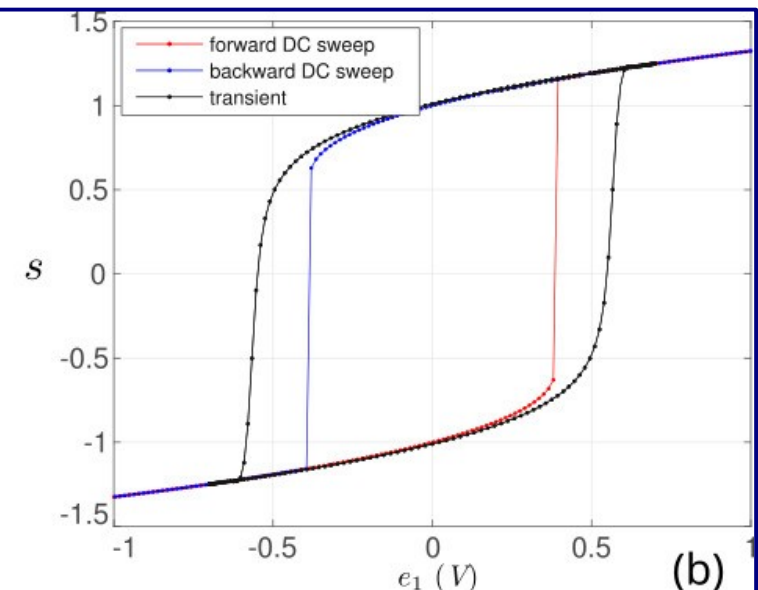
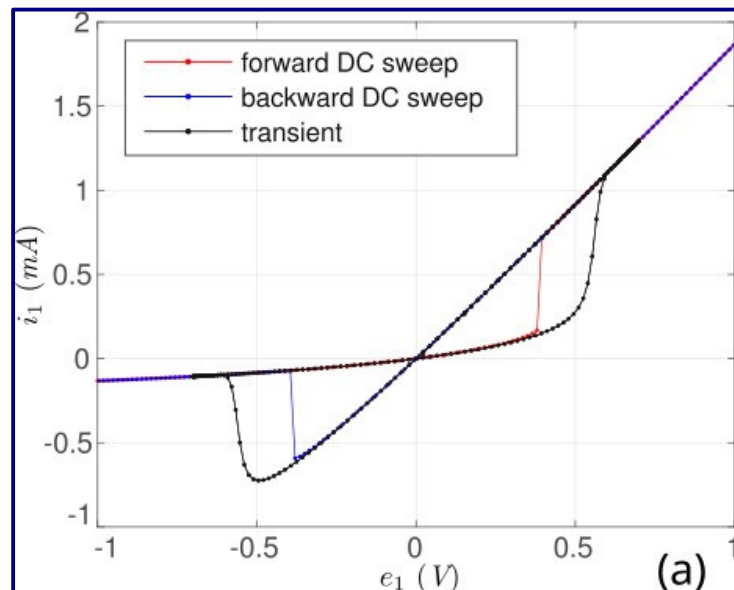
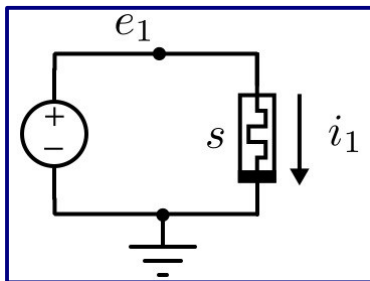
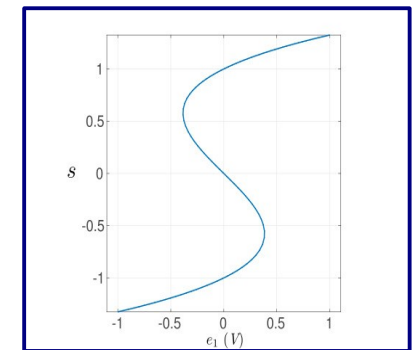


homotopy

top



side



Memristor Models

$$\frac{d}{dt}s = f_2(\mathbf{vpn}, s)$$

Available f₂:

① linear ion drift

$$f_2 = \mu_v \cdot R_{on} \cdot f_1(\mathbf{vpn}, s)$$

② nonlinear ion drift

$$f_2 = a \cdot \mathbf{vpn}^m$$

③ Simmons tunnelling barrier

$$f_2 = \begin{cases} c_{off} \cdot \sinh\left(\frac{i}{i_{off}}\right) \cdot \exp\left(-\exp\left(\frac{s-a_{off}}{w_c} - \frac{i}{b}\right) - \frac{s}{w_c}\right), & \text{if } i \geq 0 \\ c_{on} \cdot \sinh\left(\frac{i}{i_{on}}\right) \cdot \exp\left(-\exp\left(\frac{a_{on}-s}{w_c} + \frac{i}{b}\right) - \frac{s}{w_c}\right), & \text{otherwise,} \end{cases}$$

④ TEAM model

⑤ Yakopcic model

⑥ Stanford/ASU

$$f_2 = -v_0 \cdot \exp\left(-\frac{E_a}{V_T}\right) \cdot \sinh\left(\frac{\mathbf{vpn} \cdot \gamma \cdot a_0}{t_{ox} \cdot V_T}\right)$$

$$\mathbf{ipn} = f_1(\mathbf{vpn}, s)$$

Available f₁:

① $f_1 = (R_{on} \cdot s + R_{off} \cdot (1 - s))^{-1} \cdot \mathbf{vpn}$

② $f_1 = \frac{1}{R_{on}} \cdot e^{-\lambda \cdot (1-s)} \cdot \mathbf{vpn}$

③ $f_1 = s^n \cdot \beta \cdot \sinh(\alpha \cdot \mathbf{vpn}) + \chi \cdot (\exp(\gamma \cdot) - 1)$

④ $f_1 = \begin{cases} A_1 \cdot s \cdot \sinh(B \cdot \mathbf{vpn}), & \text{if } \mathbf{vpn} \geq 0 \\ A_2 \cdot s \cdot \sinh(B \cdot \mathbf{vpn}), & \text{otherwise.} \end{cases}$

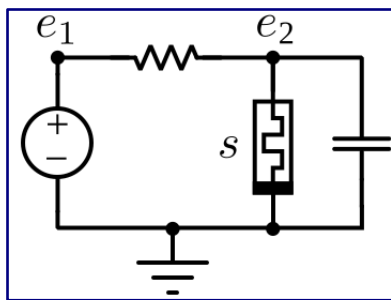
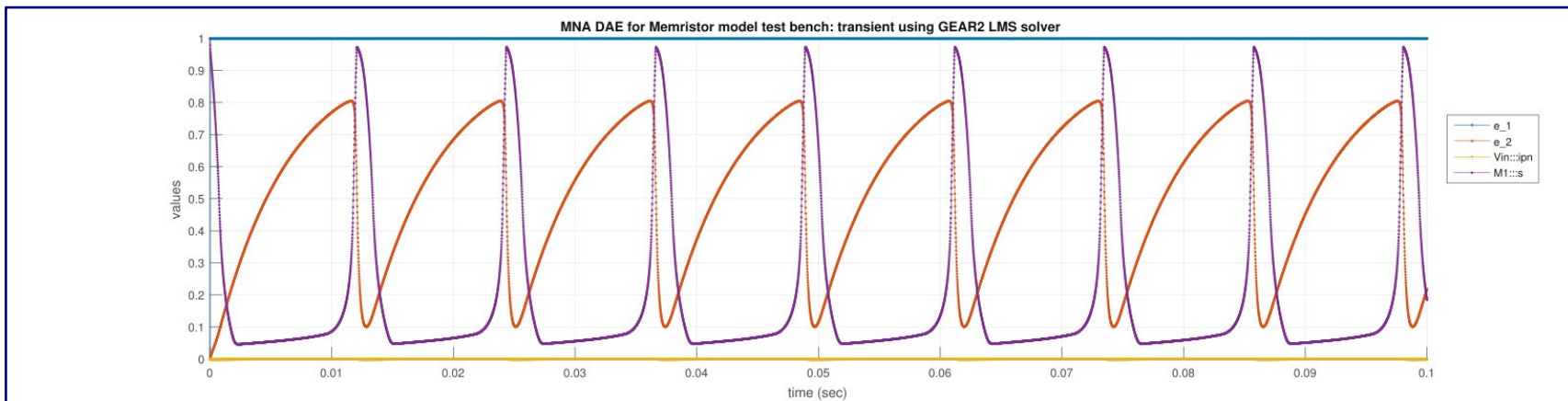
⑤ $f_1 = I_0 \cdot e^{-\text{Gap}/g_0} \cdot \sinh(\mathbf{vpn}/V_0)$
 $\text{Gap} = s \cdot \text{minGap} + (1 - s) \cdot \text{maxGap}.$

- set up boundary
- fix f₂ flat regions
- smooth, safe funcs, scaling, etc.

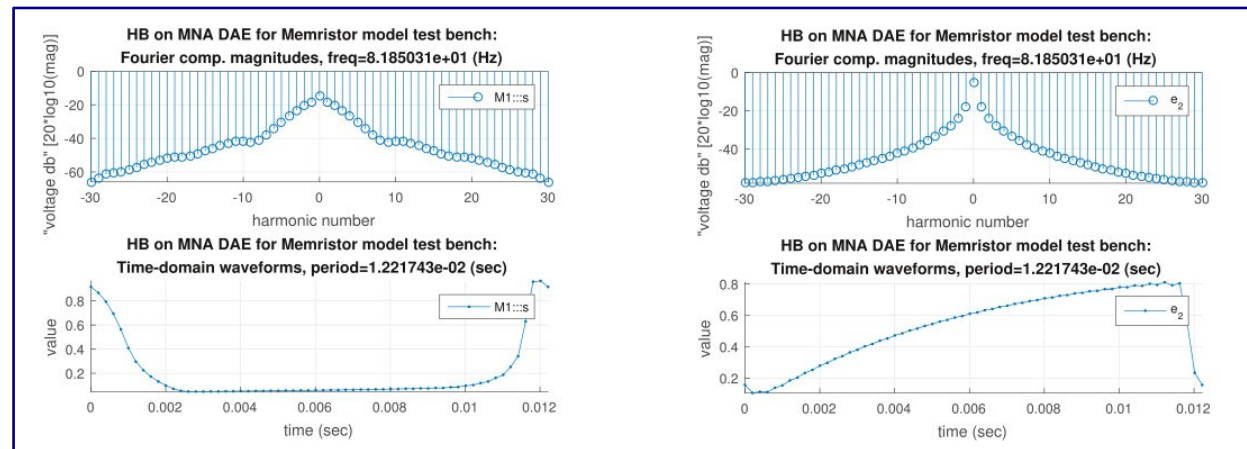
Memristor Models

A collection of 30 models:

- all smooth, all well posed
- not just RRAM, but general memristive devices
- not just bipolar, but unipolar
- not just DC, AC, TRAN, but homotopy, PSS, ...

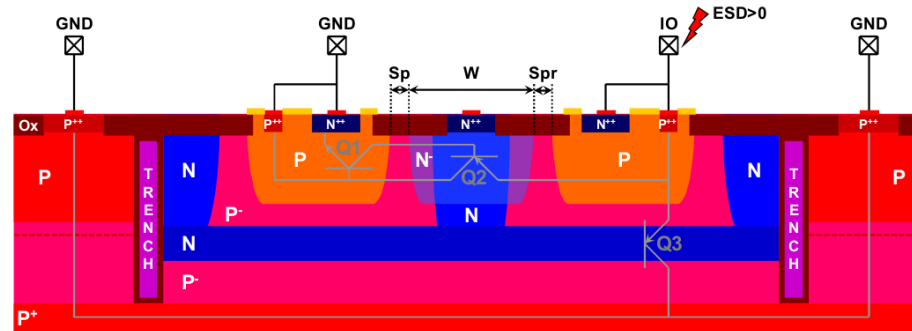


PSS using HB

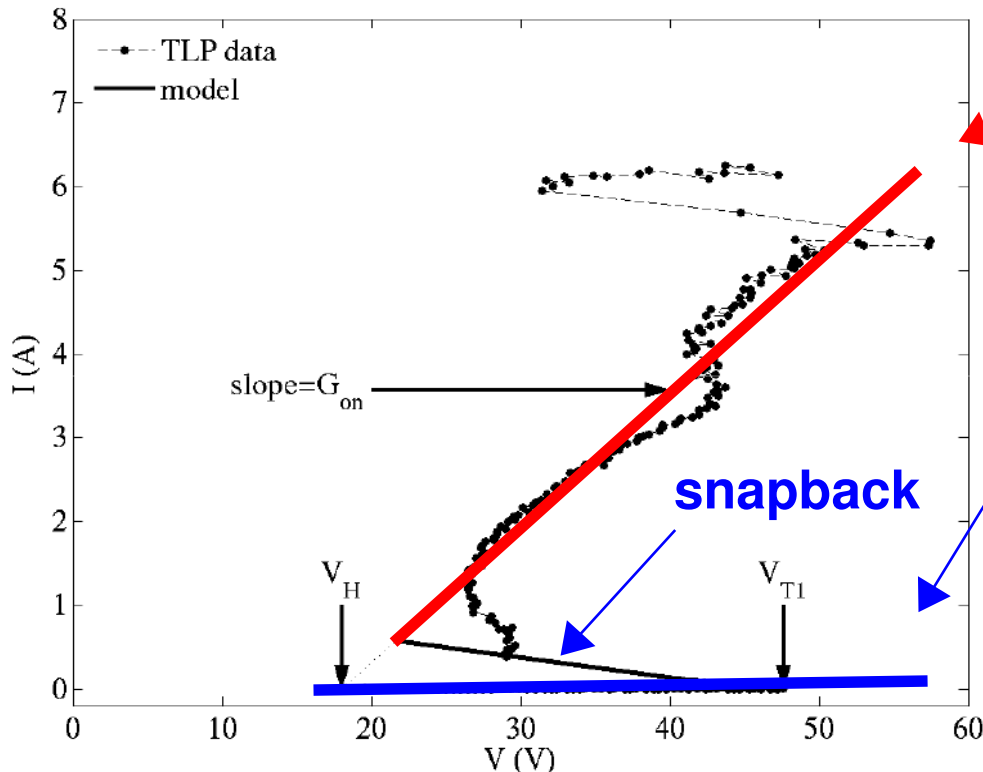


ESD Snapback Model

ESD protection device



Gendron, et al. "New High Voltage ESD Protection Devices based on Bipolar Transistors for Automotive Applications." IEEE EOS/ESD Symposium, 2011.



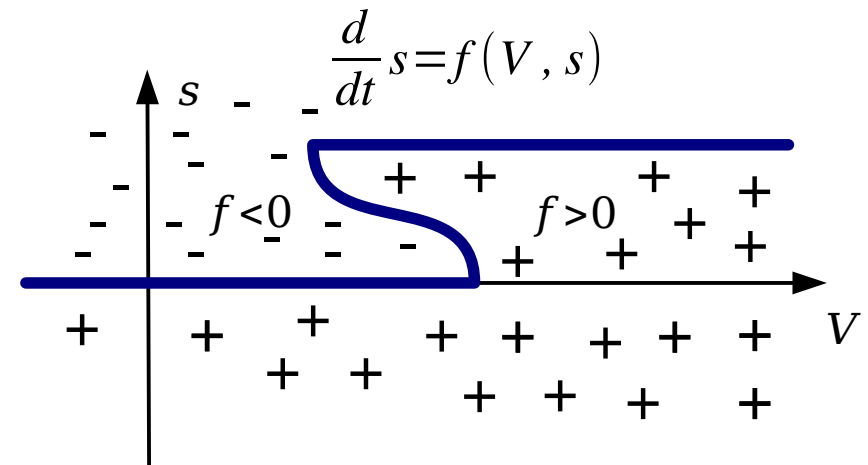
Ida/McAndrew. "A Physically-based Behavioral Snapback Model." IEEE EOS/ESD Symposium, 2012.

$$I_{on} = G_{on} \cdot (V - V_H)$$

$$I_{off} = I_s \cdot (1 - e^{-V/\phi_T}) \cdot \sqrt{1 + \frac{\max(V, 0)}{V_D}}$$

$$I = s \cdot I_{on} + I_{off}$$

internal state: indicator of impact ionization

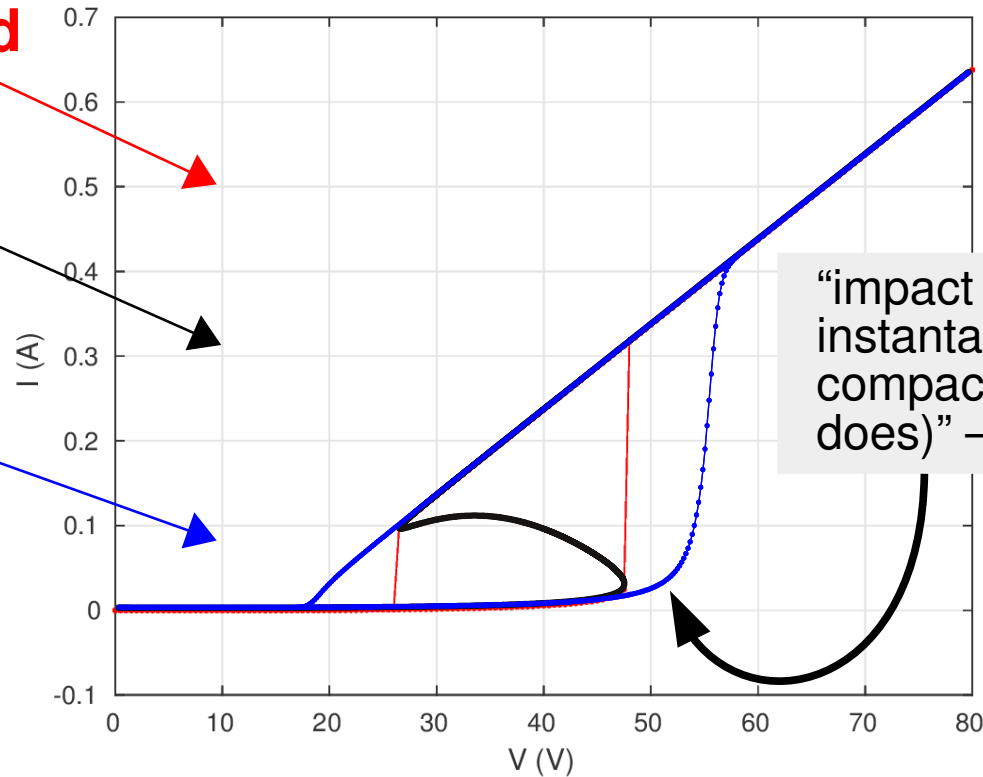


ESD Snapback Model

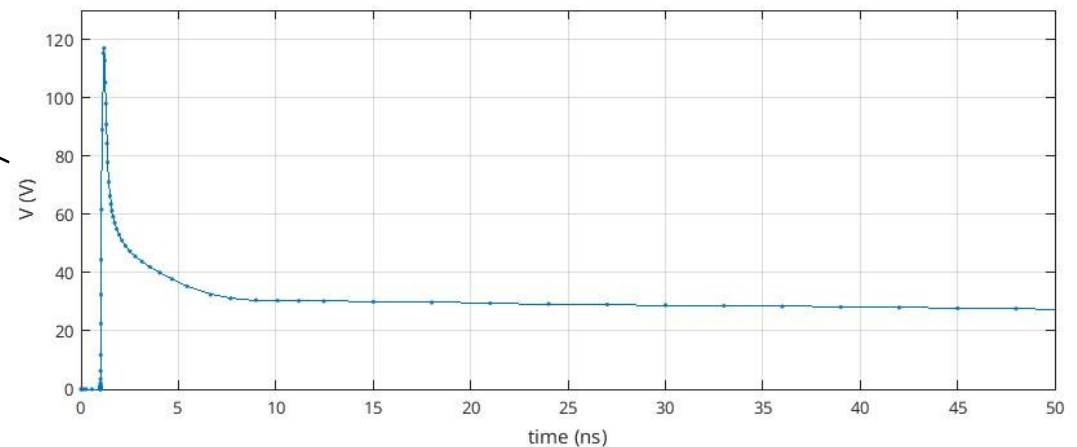
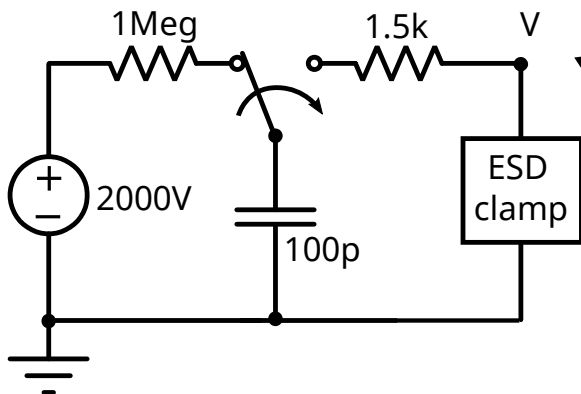
forward/backward
DC sweeps

homotopy

transient
voltage sweeps



Human Body Mode (HBM) test



Compact Model Development

