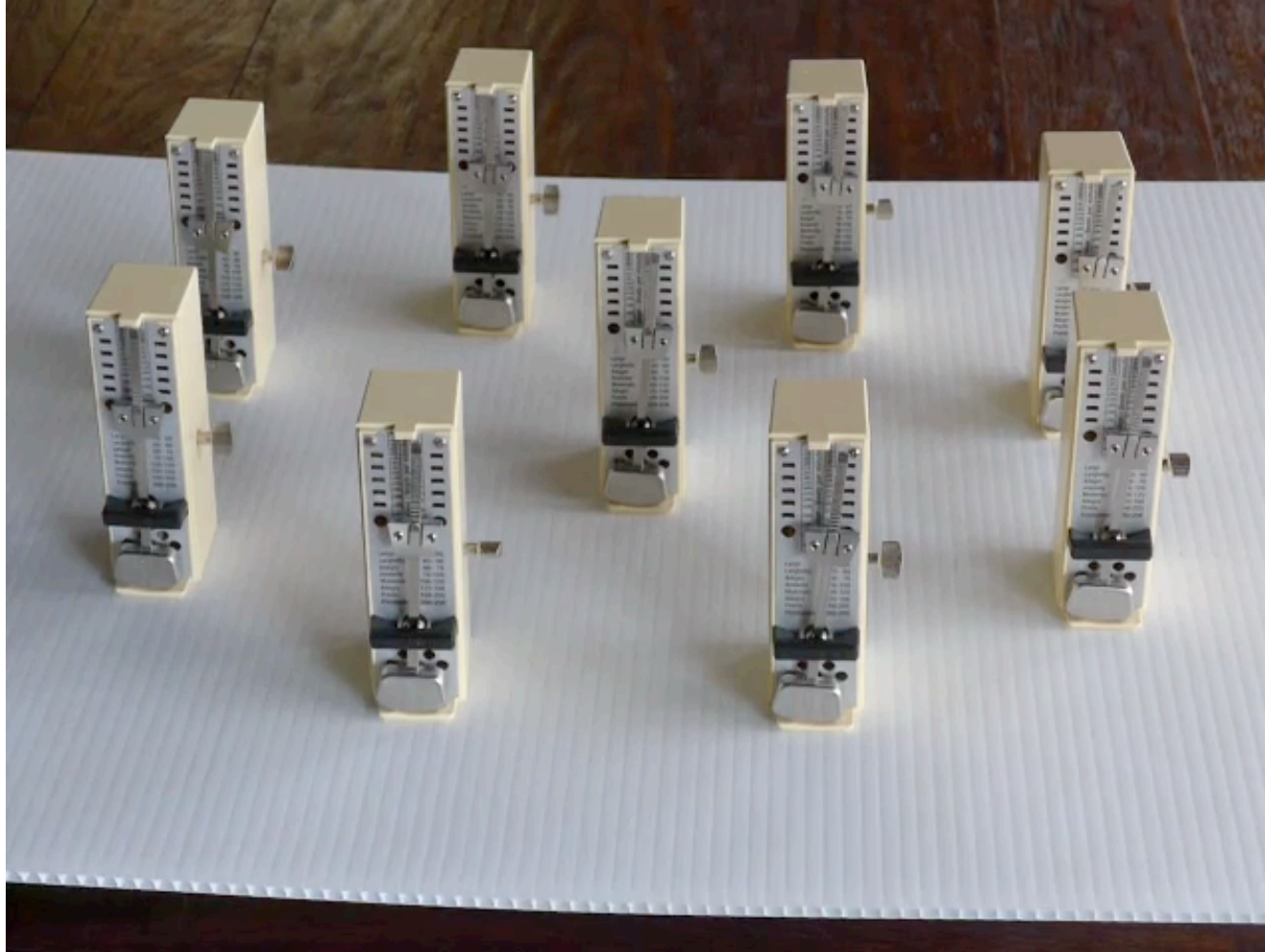


# **Does It Take Longer to Injection Lock a High-Q Oscillator?**

**Tianshi Wang and Jaijeet Roychowdhury**  
**University of California, Berkeley**

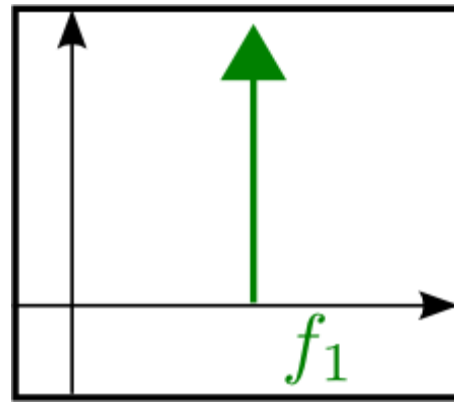
# Injection Locking

- Oscillators can synchronize in phase/frequency

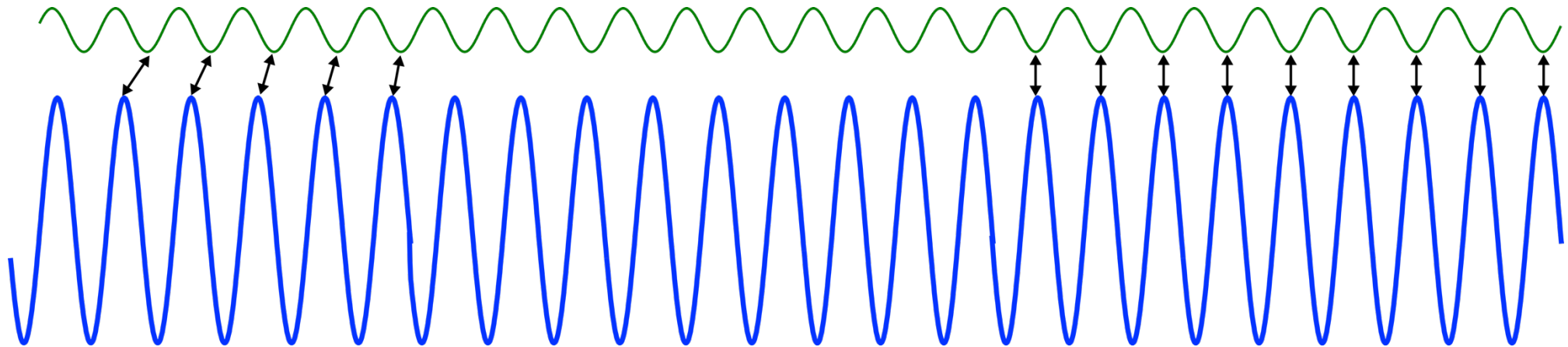
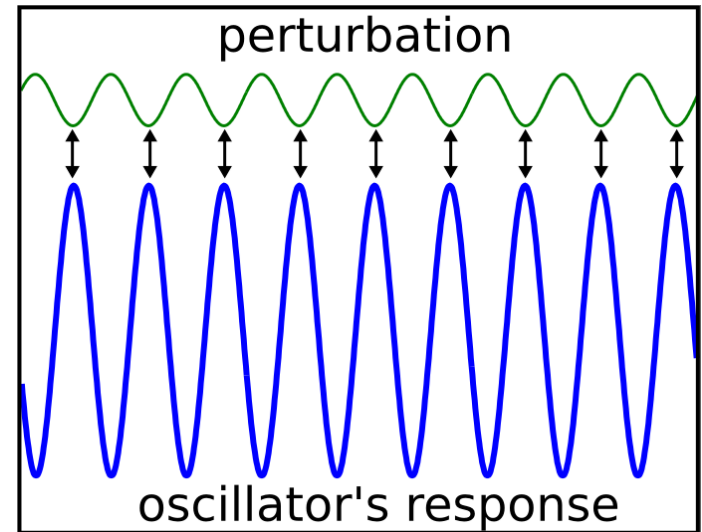
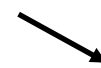


# Injection Locking

Injection Locking



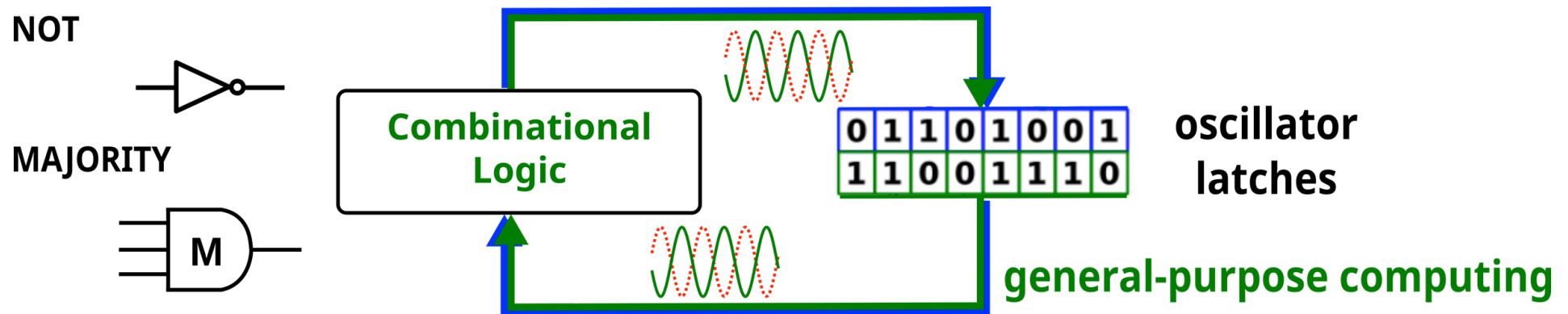
phase lock



**How fast is injection locking?**

# Does It Take Longer to Injection Lock a High-Q Oscillator?

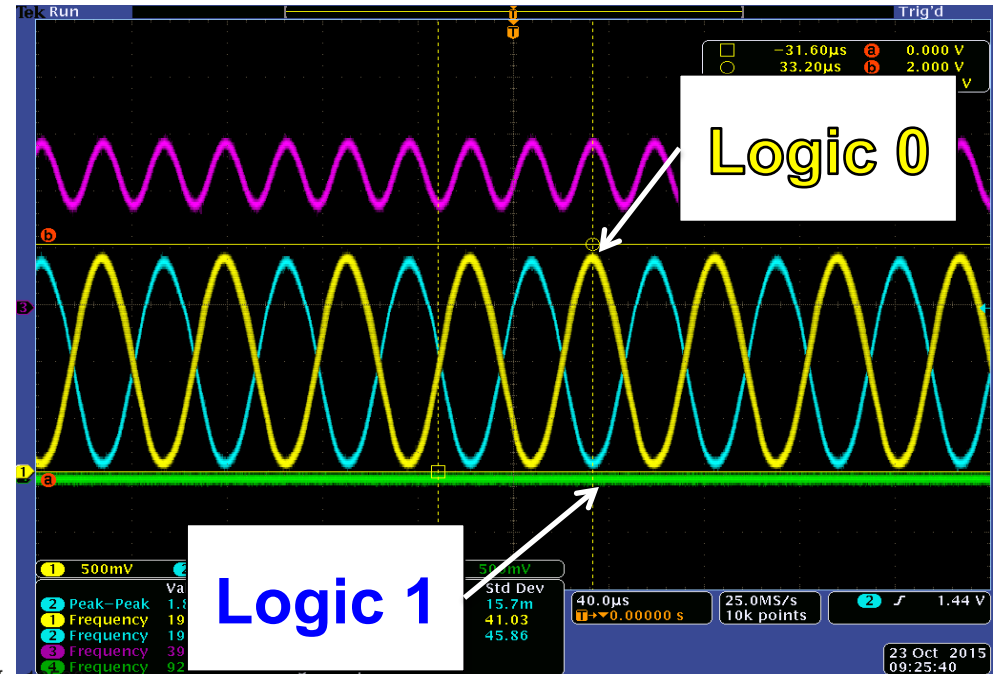
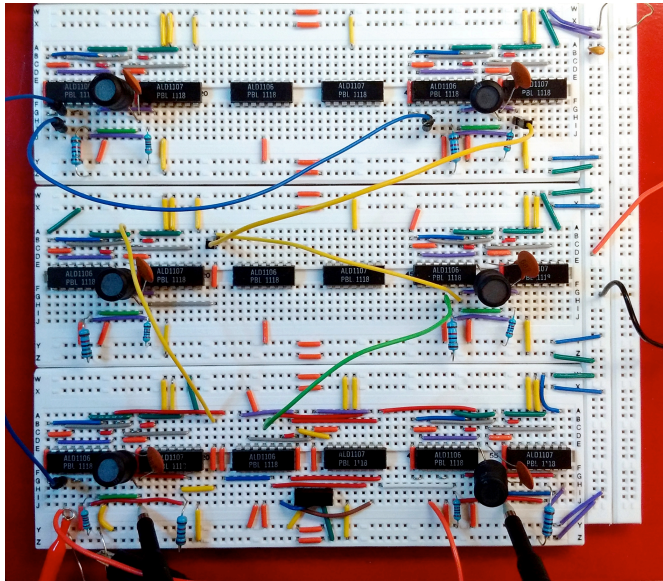
- *Why do we ask?*
  - Applications of IL:
    - quadrature oscillators
    - injection-locked PLLs
    - frequency dividers
    - optical lasers
  - **Oscillator-based Boolean Computation**



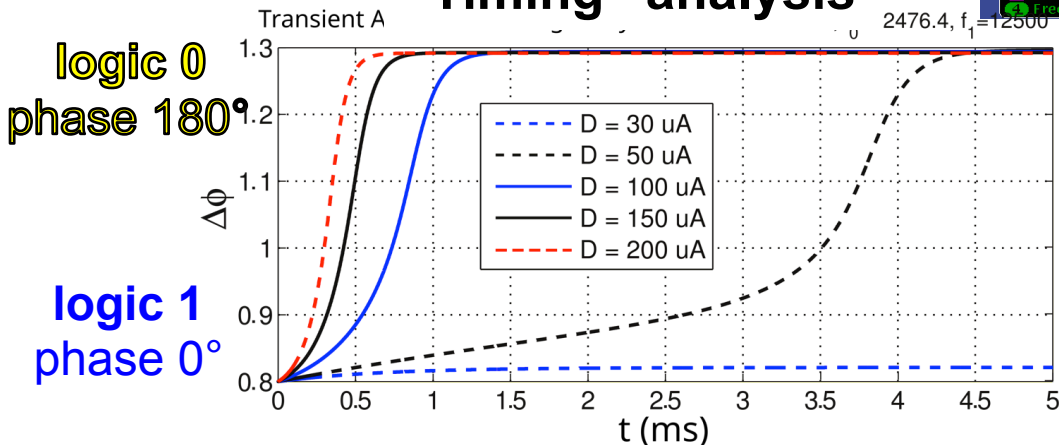
**details:** T. Wang, J. Roychowdhury, "PHLOGON: Phase-based LOGic using Oscillatory Nano-systems". Unconventional Computation & Natural Computation, 2014.

# Does It Take Longer to Injection Lock a High-Q Oscillator?

## Oscillator-based Boolean Computation



### “Timing” analysis



**Speed vs. Power**

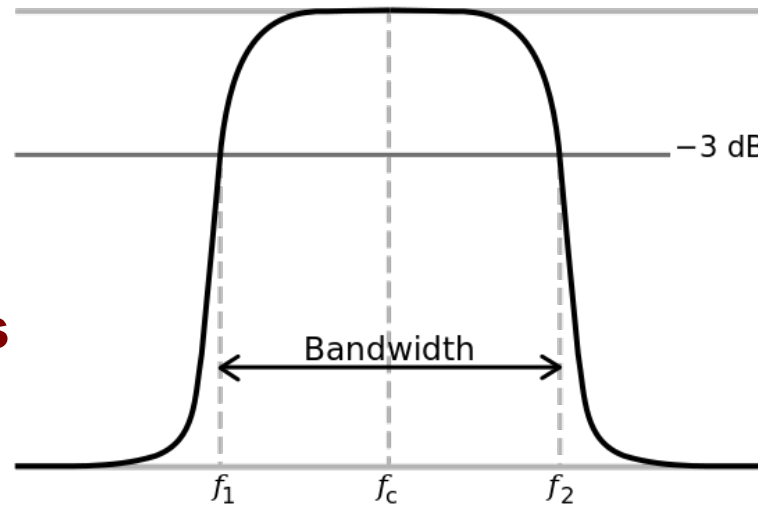
how fast is injection locking

Q factor

# Q factor of an osc.: Definitions & Confusions

- $Q \stackrel{\text{def}}{=} \frac{f_r}{\Delta f}$

**linear resonators only**



**high-Q resonator  
≠  
high-Q osc.**

- $Q \stackrel{\text{def}}{=} 2\pi f_r \times \frac{\text{Energy Stored}}{\text{Power Loss}}$

**damping systems**

**← how to measure/characterize?**

- $H(s) = \frac{\omega_0^2}{s^2 + \frac{\omega_0}{Q}s + \omega_0^2}$

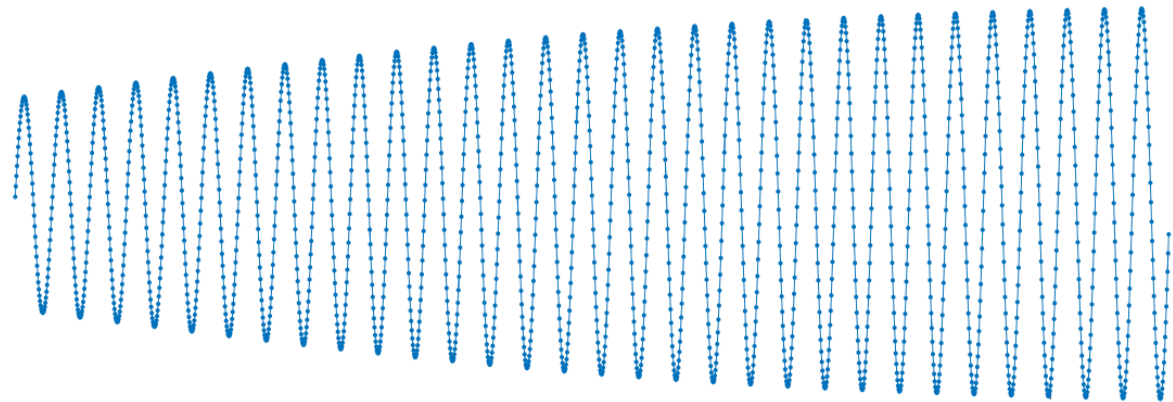
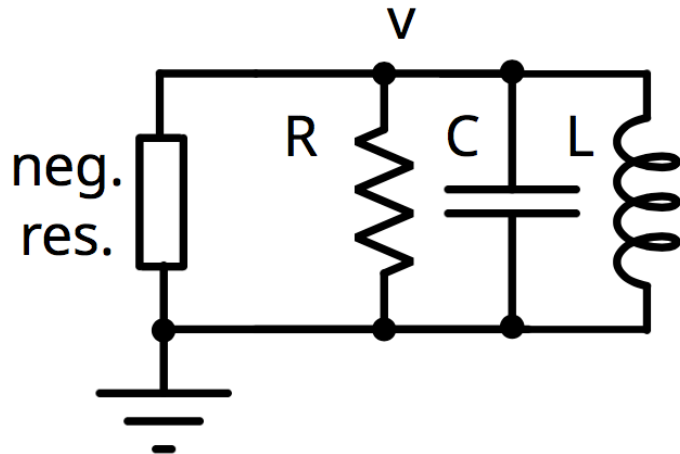
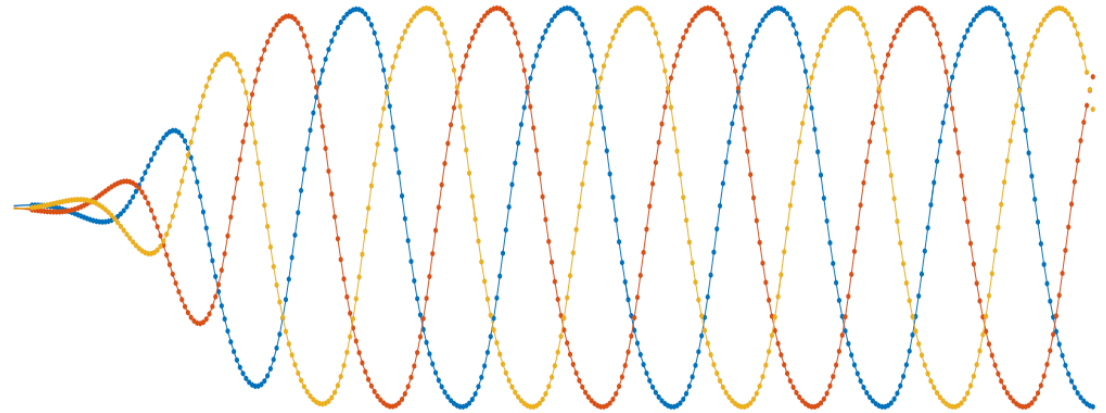
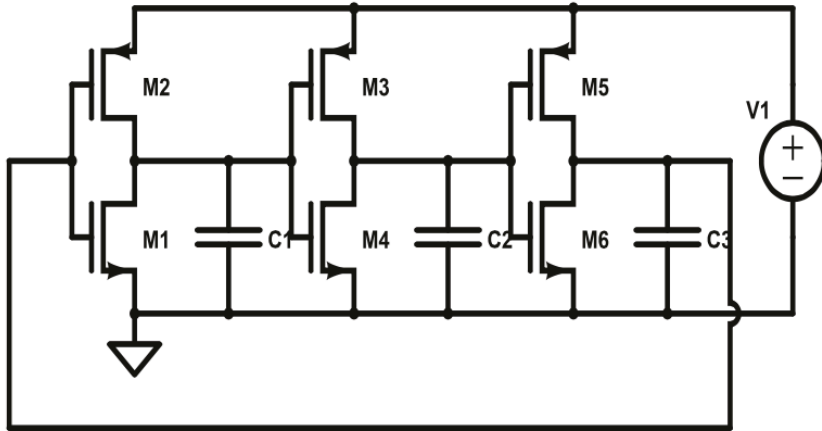
**second order linear**

- $Q = R\sqrt{\frac{C}{L}} = \frac{R}{\omega_0 L} = \omega_0 RC$

**RLC only**



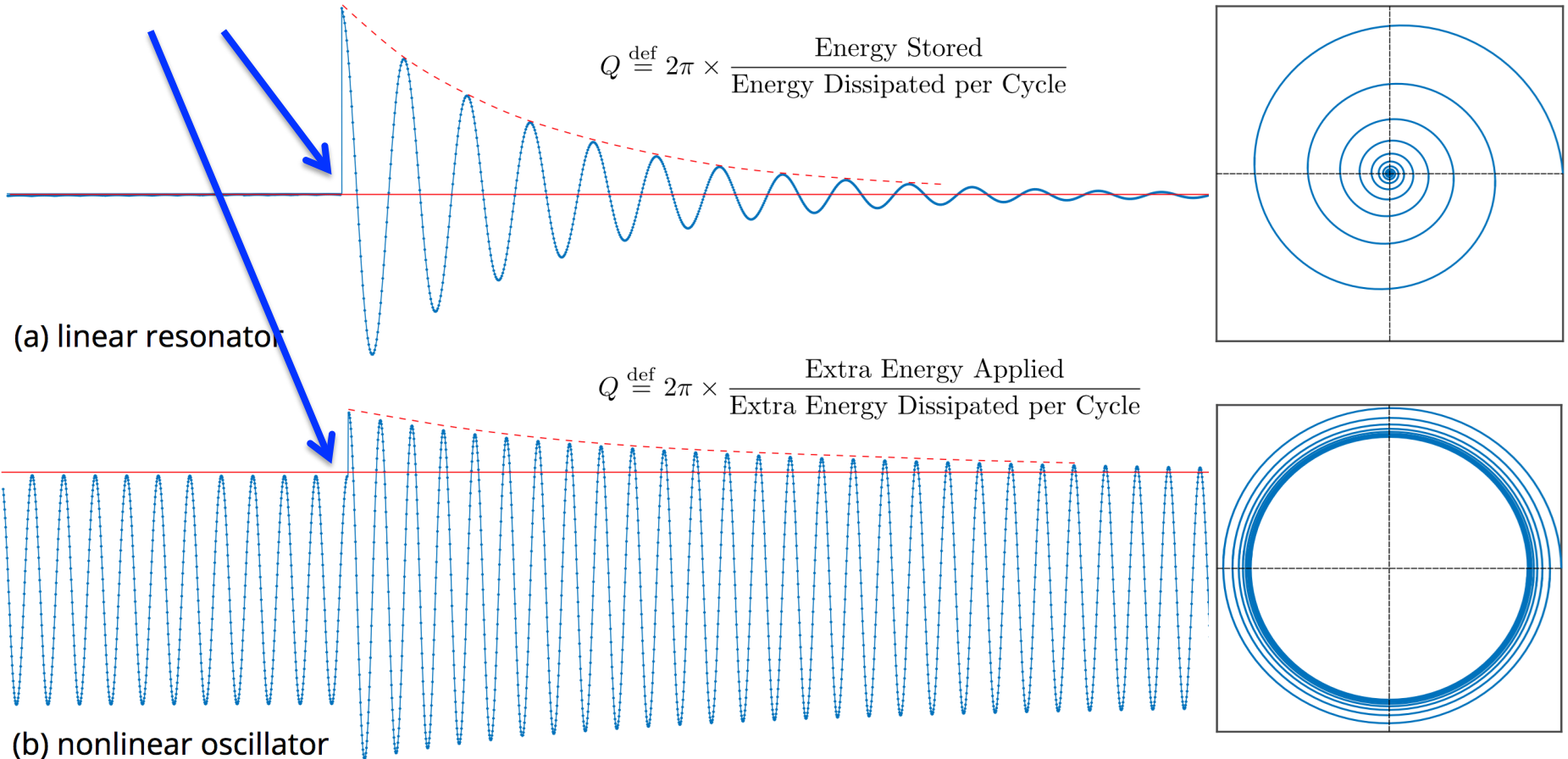
# Q factor of an oscillator: Intuition



**high-Q oscillators settle more slowly  
(in amplitude)**

# Q factor of an oscillator: Our Definition

**perturbation**



**can be measured**

**not specific to osc. types**



# Q factor: Mathematical Characterization

osc. DAE:

$$\frac{d}{dt}\vec{q}(\vec{x}(t)) + \vec{f}(\vec{x}(t)) + \vec{b}(t) = \vec{0}$$

Periodic Steady State (PSS)

$$\vec{x}_s(t) \quad \vec{x}_s(t) = \vec{x}_s(t + T)$$

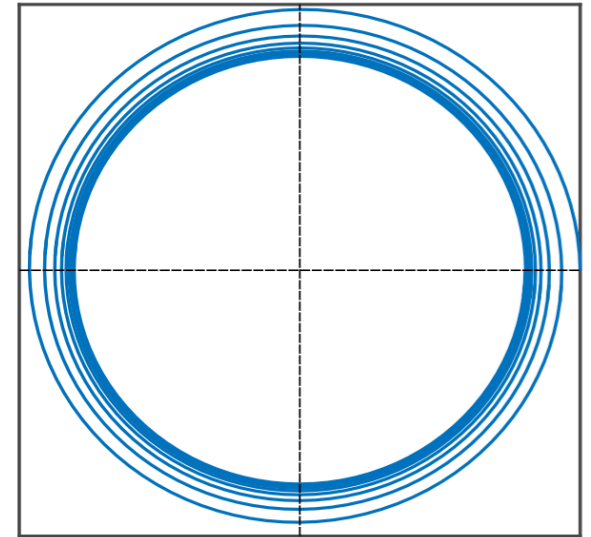
apply perturbation:

$$\vec{x}(t) = \vec{x}_s(t) + \Delta\vec{x}(t)$$

$$\frac{d}{dt}\vec{q}(\vec{x}_s(t) + \Delta\vec{x}(t)) + \vec{f}(\vec{x}_s(t) + \Delta\vec{x}(t)) = \vec{0}$$

Linear Periodically Time-Varying (LPTV) system:

$$\frac{d}{dt}\mathbf{C}(t) \cdot \Delta\vec{x}(t) + \mathbf{G}(t) \cdot \Delta\vec{x}(t) = \vec{0} \quad \mathbf{C}(t) = \left. \frac{d\vec{q}}{d\vec{x}} \right|_{\vec{x}_s(t)} \quad \mathbf{G}(t) = \left. \frac{d\vec{f}}{d\vec{x}} \right|_{\vec{x}_s(t)}$$



# Q factor: Mathematical Characterization

Linear Periodically Time-Varying (LPTV) system:

$$\frac{d}{dt} \mathbf{C}(t) \cdot \Delta \vec{x}(t) + \mathbf{G}(t) \cdot \Delta \vec{x}(t) = \vec{0}$$

Fundamental Matrix of LPTV:  $\mathbf{X}(t)$

$$\frac{d}{dt} \mathbf{C}(t) \cdot \mathbf{X}(t) + \mathbf{G}(t) \cdot \mathbf{X}(t) = \vec{0}$$

$$\mathbf{X}(0) = \mathbf{I}_n$$

$\Delta \vec{x}(T) = \mathbf{X}(T) \cdot \Delta \vec{x}(0) \longleftarrow \mathbf{X}(T)$  determines  $\Delta \vec{x}(0) \rightarrow \Delta \vec{x}(T)$

Eigenanalysis on  $\mathbf{X}(T)$

- $\lambda_{\max} = \lambda_1 = 1$
- $\lambda_2$  characterizes the decay of amplitude!

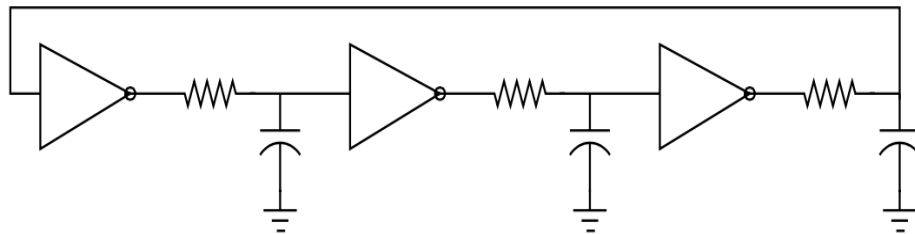
# Q factor: Mathematical Characterization

Eigenanalysis on  $\mathbf{X}(T)$

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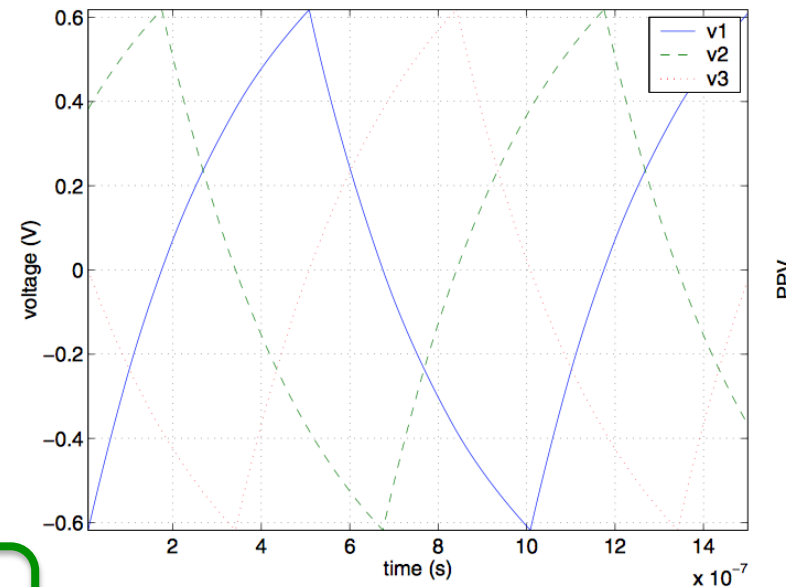
$\lambda_2^Q < 0.05$  means: after  $Q$  cycles, magnitude drops below 5%

An analytical example:



$$f(v) = \begin{cases} -A, & \text{if } v > 0 \\ A, & \text{otherwise.} \end{cases}$$

ideal ring osc.

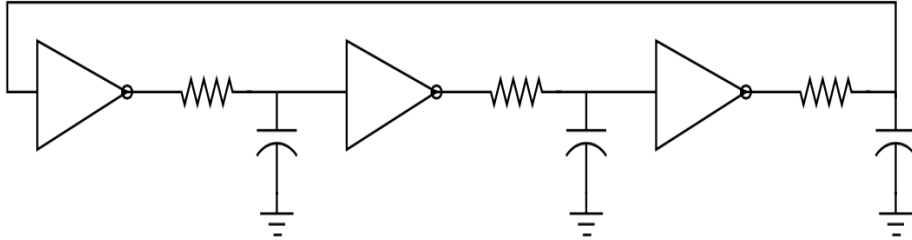


$$\lambda_2 = \left( \frac{\sqrt{5} - 1}{2} \right)^6 \approx 0.0557$$

$$Q \approx 1.1$$

**details:** Srivastava/Roychowdhury, "Analytical Equations for Nonlinear Phase Errors and Jitter in Ring Oscillators", TCAS I, 2007.

# Q factor: Numerical Results

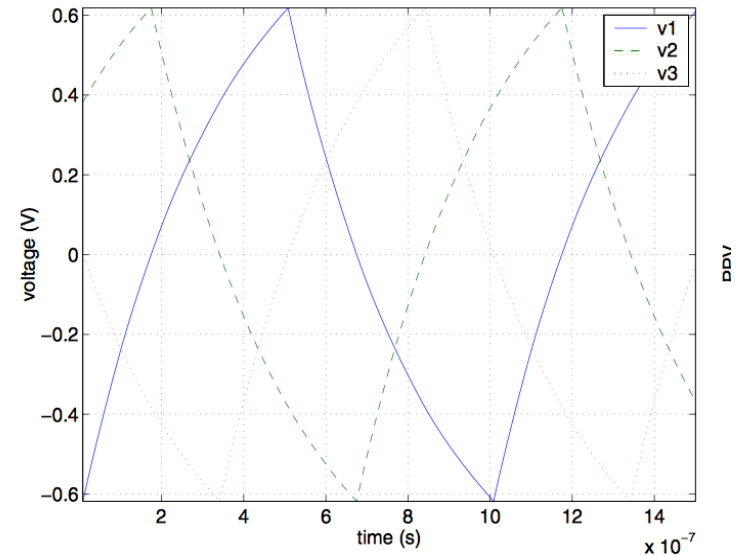


$$f(v) = \begin{cases} -A, & \text{if } v > 0 \\ A, & \text{otherwise.} \end{cases}$$

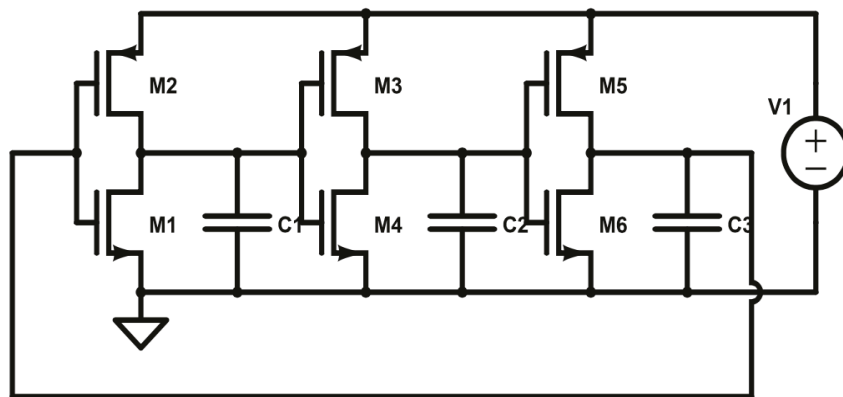
ideal ring osc.

$$\lambda_2 = \left(\frac{\sqrt{5} - 1}{2}\right)^6 \approx 0.0557$$

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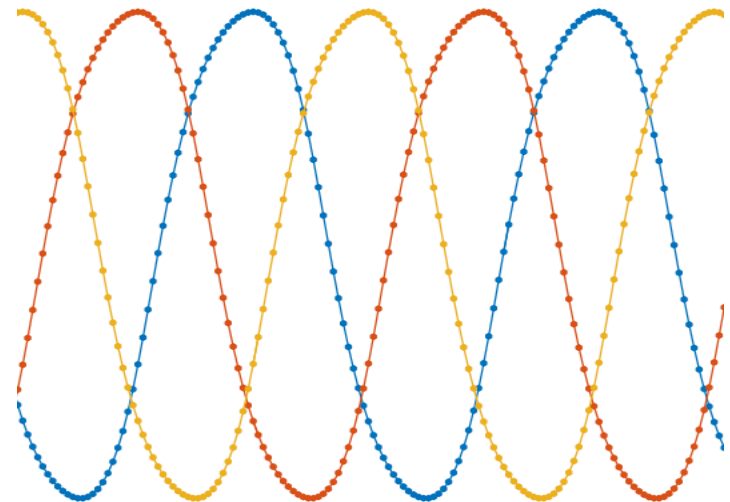


“realistic” ring osc.



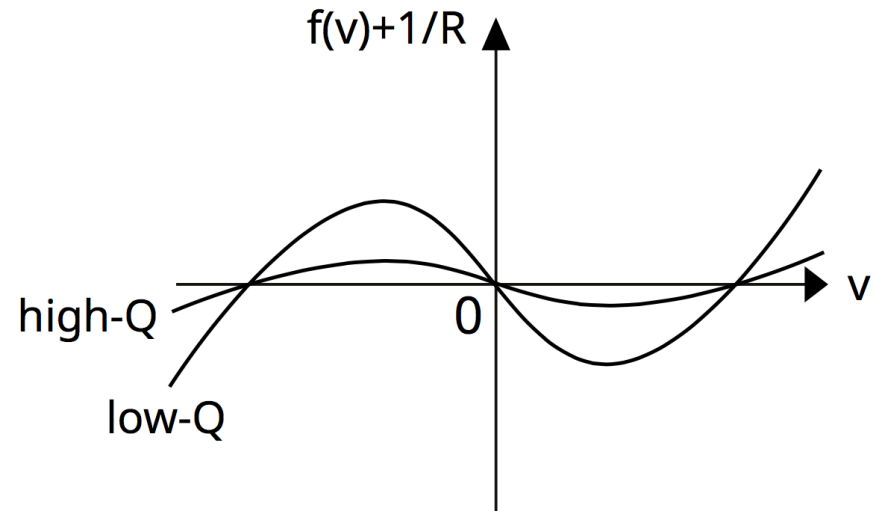
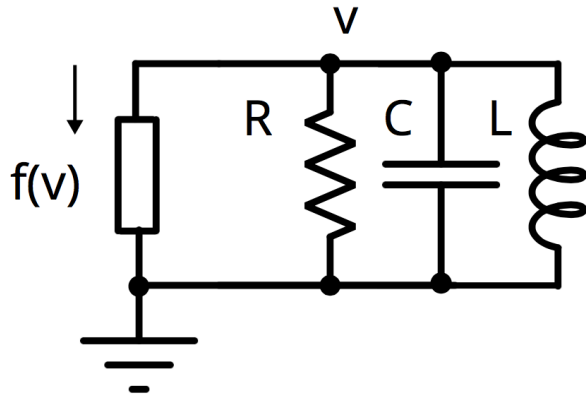
$$\lambda_2 \approx 0.067$$

$$Q \approx 1$$



# Q factor: Numerical Results

LC osc.



$$f(v) + \frac{1}{R} = K \cdot (v - \tanh(1.01 \cdot v))$$

**K = 20**  
(low-Q)

$$\lambda_2 \approx 0.11$$

$$Q \approx 1.4$$

**K = 1**  
(high-Q)

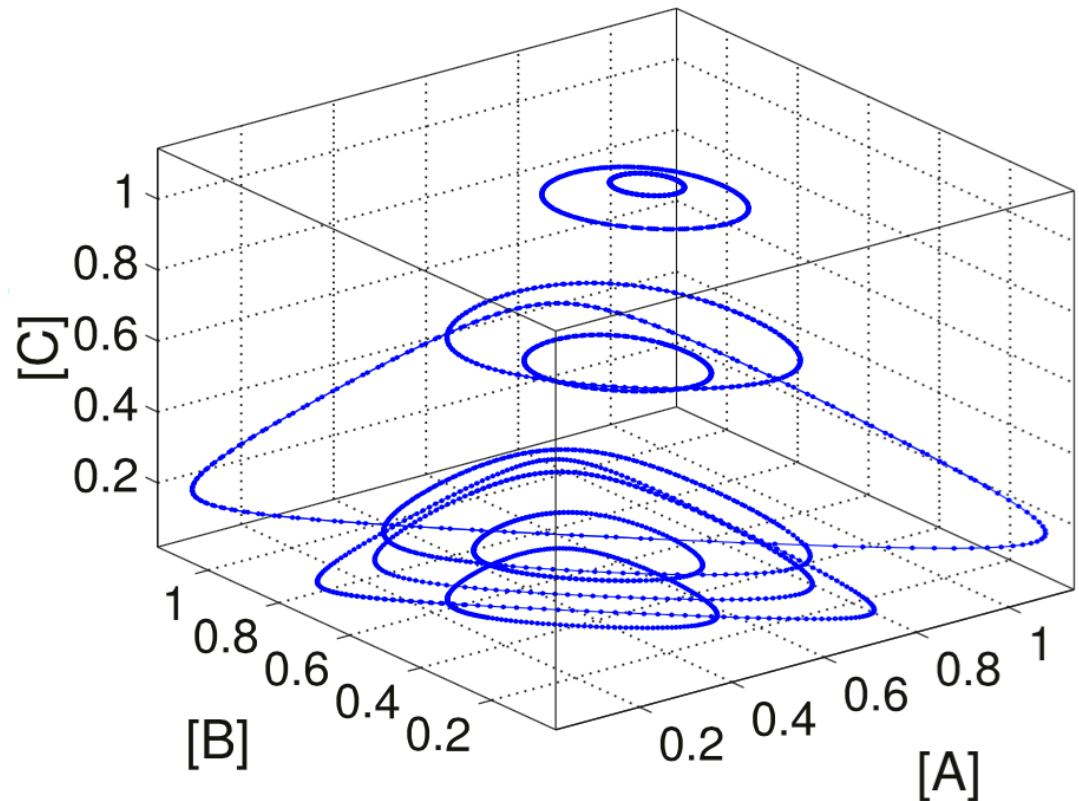
$$\lambda_2 \approx 0.83$$

$$Q \approx 16$$

# Q factor: Numerical Results

a chemical reaction osc.

Soloveichik's chemical  
reaction osc.



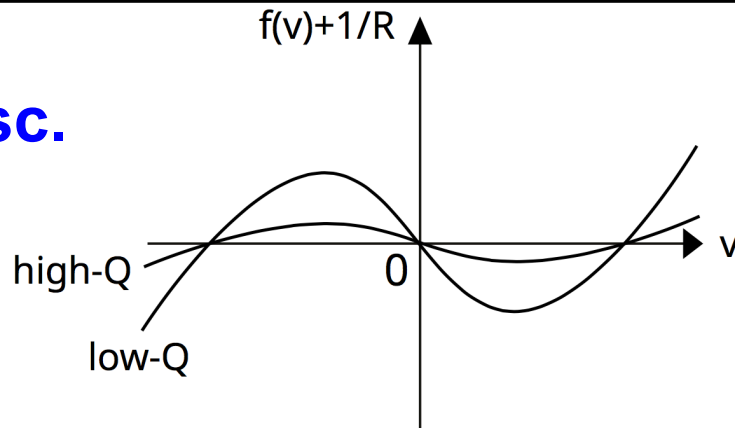
$$\lambda_2 = 1$$

not amplitude-stable



# High-Q oscillators settle more slowly in amplitude

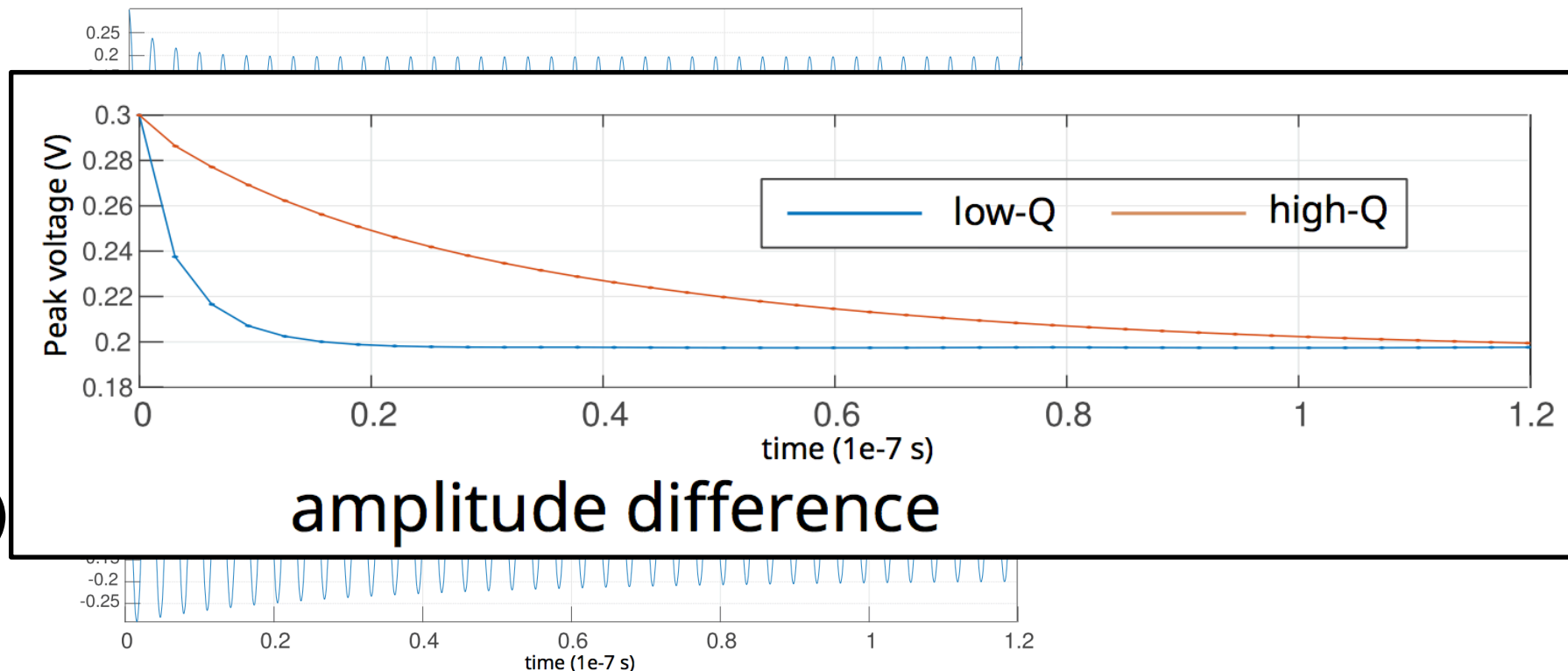
LC osc.



$$f(v) + \frac{1}{R} = K \cdot (v - \tanh(1.01 \cdot v))$$

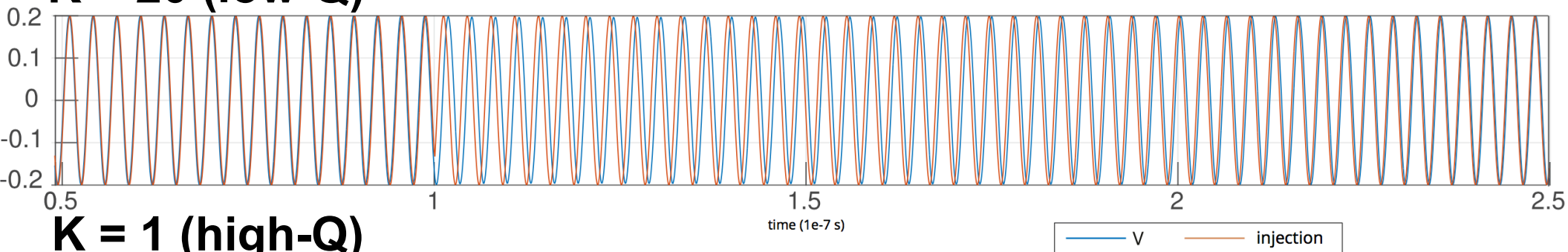
**K = 20  
(low-Q)**

**K = 1  
(high-Q)**

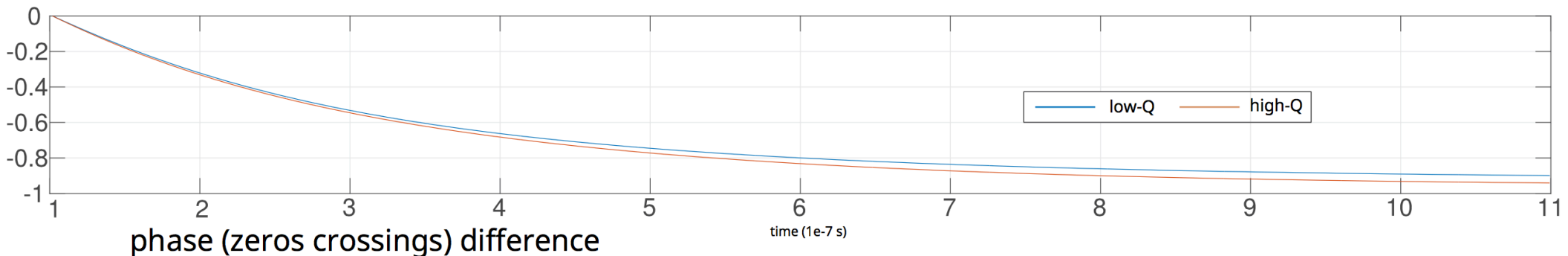
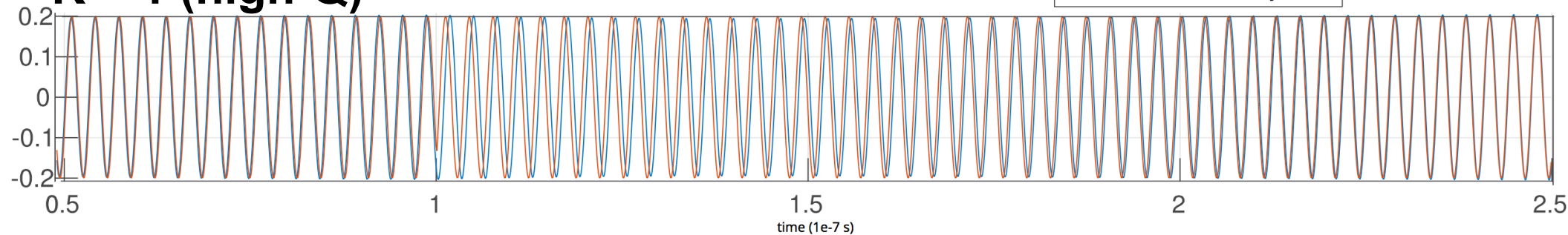


# Does It Take Longer to Injection Lock a High-Q Oscillator?

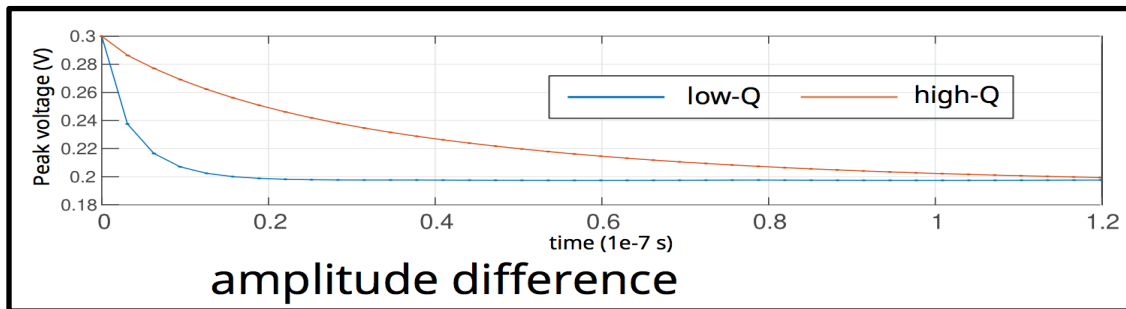
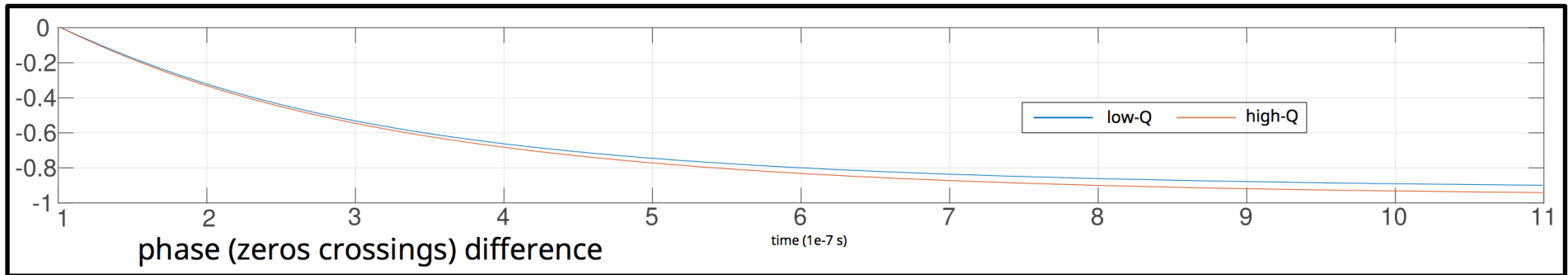
**K = 20 (low-Q)**



**K = 1 (high-Q)**



# Does It Take Longer to Injection Lock a High-Q Oscillator?



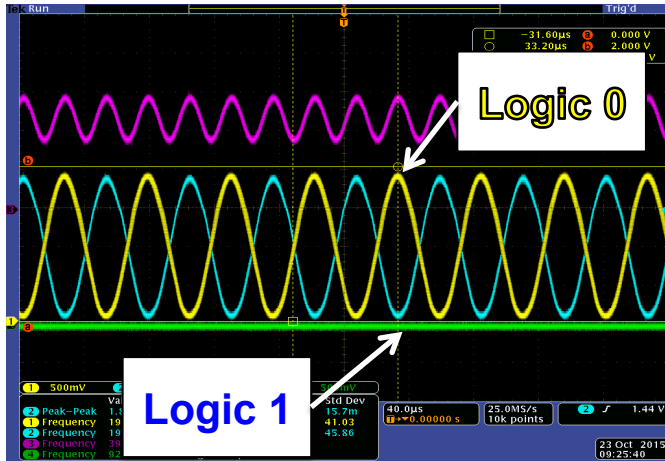
“decoupled”  
phase and amplitude  
settling behaviours

loose explanation:

$$Q \Leftrightarrow \lambda_2 \text{ of } \mathbf{X}(T)$$

phase-macromodel  $\Leftrightarrow \vec{v}_1(t)$  corresponding to  $\lambda_1$  of  $\mathbf{X}(T)$

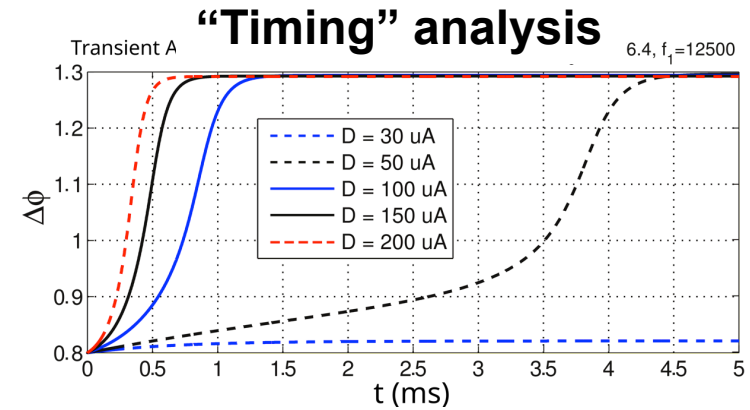
# Summary



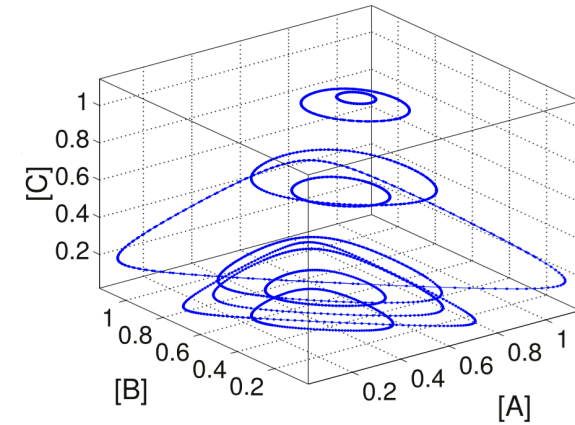
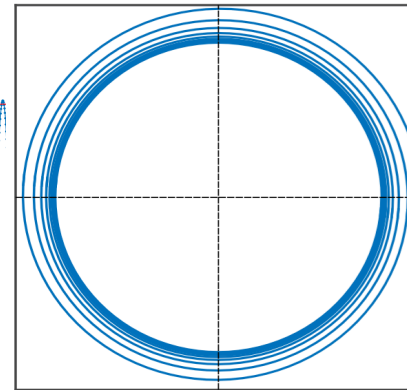
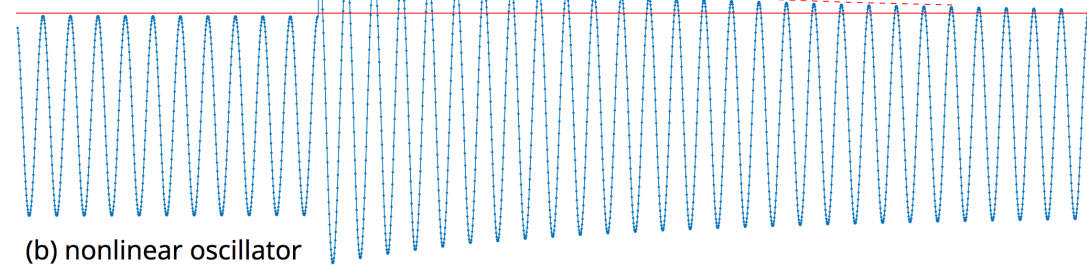
**Speed vs. Power**

how fast is injection locking

Q factor



$$Q \stackrel{\text{def}}{=} 2\pi \times \frac{\text{Extra Energy Applied}}{\text{Extra Energy Dissipated per Cycle}}$$



## LPTV analysis

$$Q \Leftrightarrow \lambda_2 \text{ of } \mathbf{X}(T)$$

**Does it take longer to injection lock a high-Q oscillator?**